# DESIGN AND FABRICATION OF A HIGH-PERFORMANCE BRAYTON CYCLE RADIAL-FLOW GAS GENERATOR

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Prepared under Contract No. NAS 3-2778 by AIRESEARCH MANUFACTURING COMPANY OF ARIZONA Phoenix, Ariz.

for Lewis Research Center

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION

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#### **FOREWORD**

The research described herein, which was conducted by the AiResearch Company of Arizona, a Division of the Garrett Corporation, was performed under NASA Contract NAS 3-2778. The work was done under the technical management of Mr. Jack A. Heller, Space Power Systems Division, Lewis Research Center, with Mr. George K. Fischer and Mr. Harold E. Rohlik, both of the Fluid System Components Division, Lewis Research Center, as technical consultants. The report was originally issued as AiResearch Report APS-5200-R.

# ABSTRACT

The program described herein consisted of analyses, design, gas bearing development and fabrication of a radial-flow gas generator (turbocompressor) for performance evaluation by the NASA. The respective turbine and compressor components, identical to those in the gas generator, were delivered in separate research packages utilizing oil-lubricated ball bearings for detail aerodynamic performance investigations. A gas generator was delivered that operated satisfactorily on its gas journal and thrust bearings at 38,500 rpm design speed at  $500^{\circ}$  F turbine inlet temperature.

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# DESIGN AND FABRICATION OF A HIGH-PERFORMANCE BRAYTON CYCLE RADIAL-FLOW GAS GENERATOR

#### AIRESEARCH MANUFACTURING COMPANY OF ARIZONA

#### SUMMARY

The NASA-Lewis Research Center is presently engaged in an investigation of Brayton-cycle space-power systems that use solar or nuclear energy as the heat source and an inert gas as the working fluid. The turbomachinery required for the system and component investigations was defined by the NASA for both radial and axial-flow machinery. Under Contract NAS3-2778, three pieces of radial turbomachinery were designed and fabricated, as follows:

Compressor and Turbine Research Packages - The two compressor and turbine research packages each include a high-performance single-stage radial wheel and attendant components and a suitable set of running gear with oil-lubricated bearings. Both research packages are to be used to evaluate component aerodynamic performance.

<u>Gas Generator</u> - This unit combines the turbine and compressor of the two research packages into a single hot unit, with the running gear including gas-lubricated bearings. The gas generator will be used to evaluate the Brayton-cycle radial turbomachinery in a ground test loop.

This report describes the selection of the gas generator design speed and the design, fabrication, inspection, instrumentation, and testing of the gas generator prior to delivery to the NASA. Shown below is the specified design point of the turbine and compressor as individual components and as included in the radial turbomachinery gas generator:

	Turbine	Compressor	Gas Generator
Working fluid	Argon	Argon	Argon
Flow rate, lbs per sec.	1.184	0.621	0.611
Turbine inlet temperature, <sup>o</sup> R	520	-	1950
Turbine inlet pressure, psia	13.2	-	13.2
Turbine total pressure ratio	1.56	-	1.56
Compressor inlet temperature, ${}^{\mathrm{o}}\!R$	-	520	536
Compressor inlet pressure, psia	-	6.0	6.0
Compressure pressure ratio	-	2.30	2.30

Two cold research packages each of the turbine and compressor were delivered to the NASA for aerodynamic performance investigations. Two gas generators were fabricated and also delivered to the NASA; one as a complete unit and the second as separate parts. Successful dynamic and mechanical integration of the thrust and journal gas bearings with the gas generator was accomplished. Prior to shipment to the NASA, the assembled unit was subjected to an Acceptance Test which demonstrated satisfactory performance on air at approximately 500°F turbine inlet temperature.

#### 1.0 INTRODUCTION

The NASA-Lewis Research Center is presently conducting an evaluation of closed, recuperated Brayton-cycle space power systems that use solar or nuclear energy as the heat source and an inert gas as the working fluid. Both axial- and radial-flow types of turbomachinery will be evaluated. This contract (NAS3-2778) calls for the design and fabrication of the following radial-flow turbomachinery:

Compressor and Turbine Research Packages - The two compressor and turbine research packages each include a high-performance single-stage radial wheel and attendant components and a suitable set of running gear with oil-lubricated bearings. Both research packages are to be used to evaluate component aerodynamic performance.

Gas Generator - This unit combines the turbine and compressor of the two research packages into a single hot unit, with the running gear including gas-lubricated bearings. The gas generator will be used to evaluate the Brayton-cycle radial turbomachinery in a ground test loop.

The gas generator is but one of the components utilized in the closed Brayton-cycle space power system. However, it is perhaps the most critical from a performance and reliability standpoint. The gas generator consists of a single-stage radial compressor utilized for the compression of the inert working fluid (argon) mounted on a shaft supported by gas journal and thrust bearings, driven by a single-stage, radial-inflow power turbine (mounted on the same shaft). The gas, partially expanded, is exhausted from the gas generator compressor drive turbine into a second-stage free turbine which drives an alternator on the same shaft. This latter package is separate from the gas generator unit.

The contract effort, performed to design, fabricate, and acceptance test the radial-flow gas generator, is summarized in Section 3.0 of this report. The program included the scaling of existing AiResearch turbine and compressor designs, and development of the mechanical and dynamic integration of the gas bearings into the gas generator.

The significance of the program is the integration of gas bearings with turbomachinery that culminates as a gas-bearing gas generator designed for operation on inert gas in a zero-g environment--a first of its kind. Gas bearings appear to be a promising solution to the bearing requirements of long-life Brayton-cycle space power turbomachinery.

The guidance and assistance given to this contractor by Messrs. J. A. Heller, H. E. Rohlik, and G. K. Fischer of NASA-Lewis are acknowledged. The technical assistance and consultation provided by The Franklin Institute (Dr. E. J. Gunter, Jr.), and by Dr. V. Castelli, in the design of gas journal bearings is also acknowledged.

#### 2.0 SELECTION OF DESIGN SPEED

Figure 1 shows a schematic of the NASA Brayton-cycle space power system. Contract NAS3-2778 calls for the design and fabrication of a turbine research test package, a compressor research test package, and a gas generator with the same aerodynamic components as were used in the test packages, As specified by the contract, the gas generator and research test packages have identical design conditions when corrected mass-flow rates are compared. Table 1 presents a summary of the design conditions as specified by the contract. In addition to the conditions listed in Table 1, the most important remaining turbomachinery variables are:

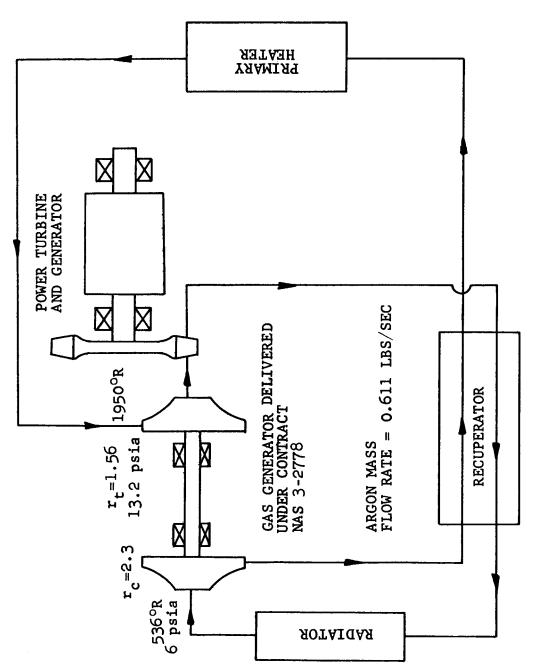
- (a) Shaft speed, N<sub>1</sub>
- (b) Compressor specific speed,  $N_{S_c}$

From the expression of compressor specific speed

$$N_{S_{c}} = \frac{N_{1}}{60} \left(\frac{1}{R_{1}T_{1}}\right)^{\frac{1}{4}} \left(\frac{m}{P_{1}}\right)^{\frac{1}{2}} \left[\frac{(\gamma - 1)M}{\gamma g(r_{c}^{\theta_{1}} - 1)}\right]^{\frac{3}{4}}$$

it can be seen that the compressor specific speed is a function only of shaft speed, since the remaining variables are fixed by the contract. (A list of the symbols used throughout this report can be found in the Glossary, Appendix I.) Therefore, the shaft speed is the only remaining variable to be specified.





NASA BRAYTON-CYCLE-POWER SYSTEM

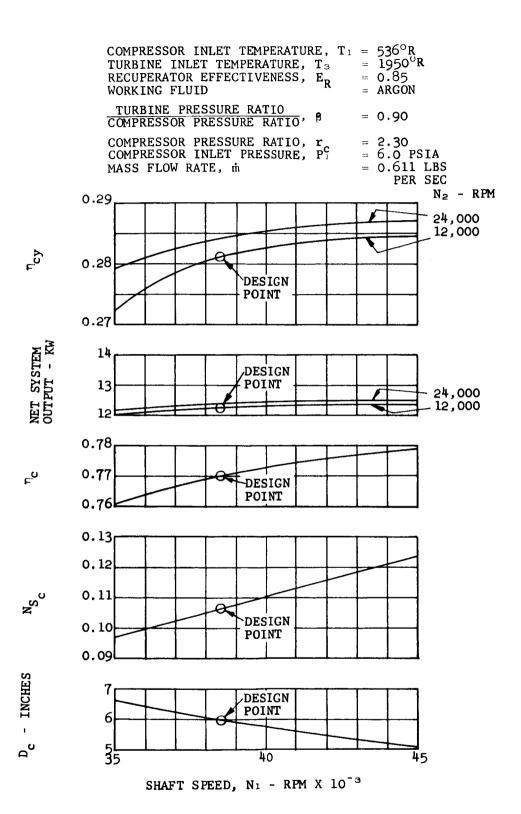
TABLE 1

DESIGN PARAMETERS FIXED BY CONTRACT NAS 3-2778

	Turbine <u>Package</u>	Compressor Package	Gas Generator
Working fluid	Argon	Argon	Argon
Mass flow rate, W -1bs per sec.	1.184	0.621	0.611
Turbine inlet temperature, $T_3$ , $^{\circ}R$	520	-	1950
Turbine inlet pressure, $P_3$ , psia	13.2	-	13.2
Turbine pressure ratio, r <sub>t1</sub>	1.56	-	1.56
Compressor inlet temperature, $T_1$ , ${}^{\circ}R$	~	520	536
Compressor inlet pressure, $P_1$ , psia	-	6.0	6.0
Compressor pressure ratio, r <sub>c</sub>	om	2.30	2.30
Corrected mass flow rate:			
W $\sqrt{\theta}/\delta$ turbine, lbs per sec.	1.318		1.318
W $\sqrt{\theta}/\delta$ compressor, lbs per sec.	-	1.521	1.521

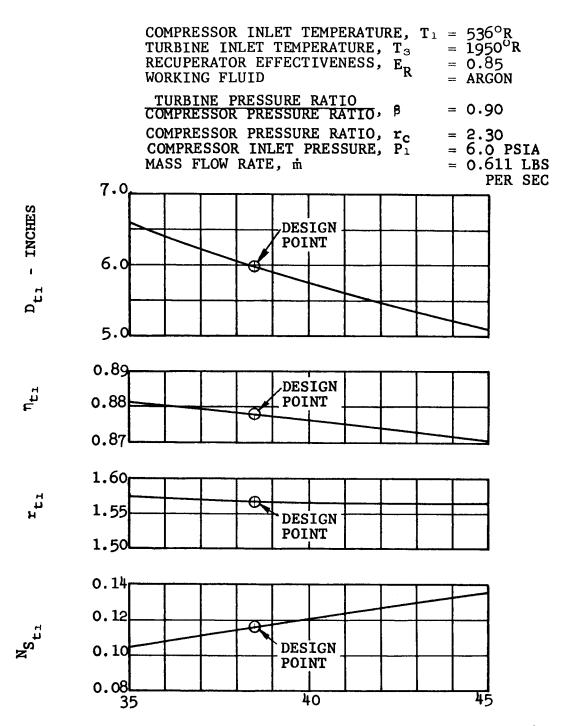
With the design-point conditions listed in Table 1, a recuperator effectiveness ( $E_R$ ) of 0.85, and a pressure-loss parameter ( $\mathbf{g}$ ) of 0.90, a gas generator design-point study was conducted to establish the gas generator thermodynamic and aerodynamic operating conditions. Figures 2 and 3 illustrate the variation of wheel diameters, component and cycle efficiencies, component specific speeds, and turbine pressure ratio over a range of shaft speeds with the turbine and compressor matched. As noted on the figures, a shaft speed of 38,500 rpm was selected as discussed below.

- (a) The compressor specific speed of 0.106, corresponding to a shaft speed of 38,500 rpm, makes AiResearch compressor experience with similar specific speeds directly applicable. A more favorable specific speed of 0.09, based on a system weight optimization to reduce the weight 5 percent, would result in a speed of 33,000 rpm, which is undesirable, as discussed in (c) below.
- (b) Reasonable adiabatic efficiencies occur for the compressor and turbines at a shaft speed of 38,500 rpm, whereas at lower speeds the component efficiency and, thus, the cycle efficiency drop off rapidly.
- (c) Turbine and compressor wheel diameters of 6 inches occur at a shaft speed of 38,500 rpm with reasonably obtainable adiabatic efficiencies. An increase in the shaft speed would reduce the wheel size and result in more restrictive manufacturing tolerances necessary to maintain hydraulically smooth aerodynamic passages.



COMPRESSOR DESIGN POINT STUDY RESULTS

FIGURE 2



SHAFT SPEED, N<sub>1</sub> - RPM X 10<sup>-3</sup>

TURBINE DESIGN POINT STUDY RESULTS FIGURE 3

#### 3.0 GAS GENERATOR DESIGN

# 3.1 Gas Generator Description

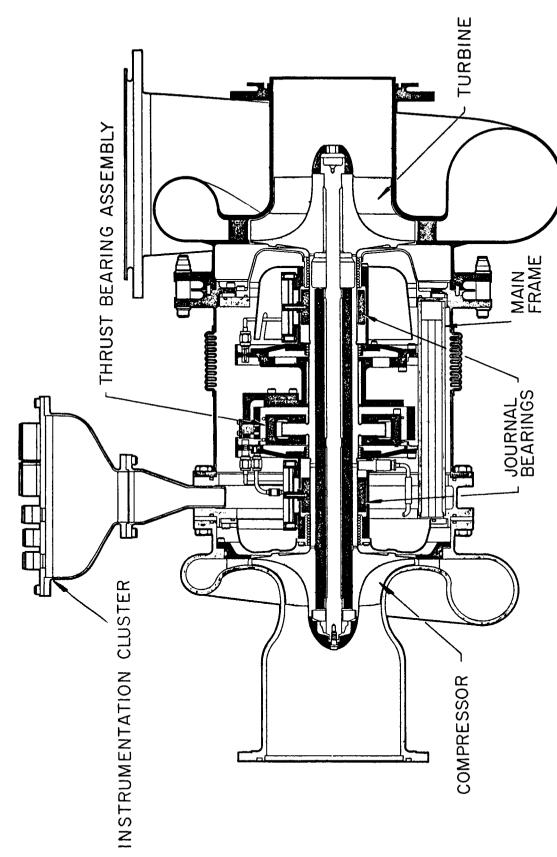
Figure 4 shows a schematic of the final gas generator configuration. The compressor and turbine wheels are mounted on a common shaft into which is incorporated a double-acting thrust bearing slider. Pivoted-pad gas-journal bearings support the shaft, one on each side of the thrust bearing next to the turbine and compressor wheels. These bearings are of the hydrodynamic type (self acting) with hydrostatic lift-off capability for starting and stopping. Between the journal bearing carriers are located the hydrostatic and hydrodynamic thrust bearing stators. The wheels, shaft, and bearings are mounted in the main frame, on which is also mounted the compressor scroll and diffuser and the turbine nozzle and scroll.

The following sections describe the design and development of the various components incorporated into the gas generator. Design details of the turbine and compressor have been minimized in the interest of brevity. However, the gas bearing development and integration of the components are included.

#### 3.2 Compressor and Turbine

The compressor and turbine components of the gas generator were first designed, fabricated, and tested on cold research packages shown in Figures 5 and 6.

The compressor research package consists of a 6.0-inch-diameter radial impeller with attendant scroll and diffuser mounted on an oilbearing test rig. Performance testing was accomplished on this rig and cutback tests were run to determine the optimum impeller cutback for the design conditions. Figure 7 shows the final map for the compressor. A complete discussion of the compressor design,



NASA BRAYTON-CYCLE RADIAL GAS GENERATOR FIGURE 4

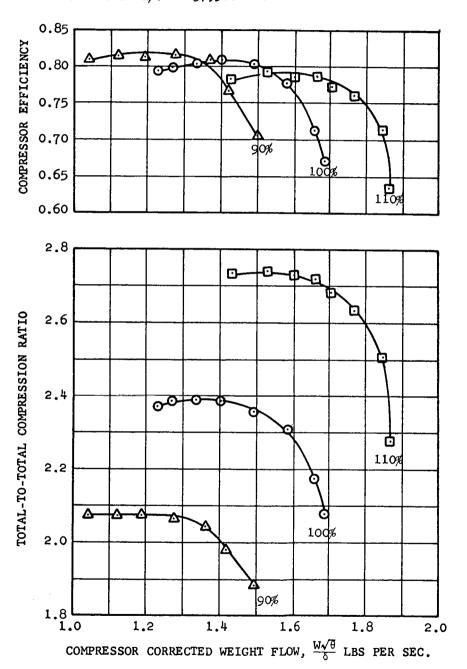


NASA COMPRESSOR RESEARCH PACKAGE FIGURE 5



NASA TURBINE RESEARCH PACKAGE FIGURE 6

TEST FLUID - ARGON COMPRESSOR INLET TOTAL PRESSURE - 12.0 to 12.5 in. Hg ABS COMPRESSOR INLET TOTAL TEMPERATURE -  $536^{\circ}$ R 100 PERCENT N/ $\sqrt{\theta}$  = 37,900 RPM



6-IN.-DIAMETER COMPRESSOR TEST RESULTS FIGURE 7

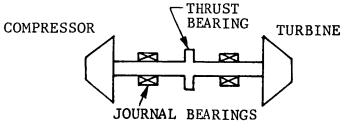
fabrication, and acceptance testing can be found in NASA Report CR-54368 entitled <u>Design and Development of a High-Performance Brayton-Cycle Compressor Research Package</u> (AiResearch Report APS-5109-R). Two compressor research packages were delivered to the NASA.

The turbine research package consists of a 6.0 inch diameter radial turbine wheel with attendant scroll and nozzle mounted on an oil-bearing test rig. Development testing was accomplished on this rig. A complete discussion of the turbine design, fabrication, and acceptance testing can be found in NASA Report CR-54367 entitled Design and Development of a High-Performance Brayton-Cycle Turbine Research Package (AiResearch Report APS-5108-R). Two turbine research packages were delivered to the NASA.

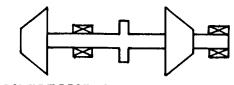
# 3.3 Dynamic Analysis

At the initiation of the gas-generator design, four possible gas-bearing/turbine and compressor wheel configurations were analyzed to determine the best configuration from critical speed and design considerations. The four systems, shown in Figure 8, consisted of a double overhung system, a compressor overhung system, a turbine overhung system, and a system wherein the bearings are mounted outside the turbine and compressor wheels. Of the four configurations analyzed, the double overhung system was chosen for continued analysis since it presented fewer overall design problems.

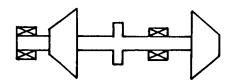
A bearing load and critical speed analysis was then conducted for the double overhung system with a range of bearing spacings (6.0 to 14.5 inches) and overall resilient gas bearing spring rates (5,000 to 20,000 pounds per inch). The resiliently mounted



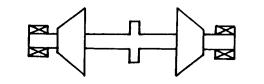
DOUBLE OVERHUNG SYSTEM



COMPRESSOR OVERHUNG SYSTEM



TURBINE OVERHUNG SYSTEM



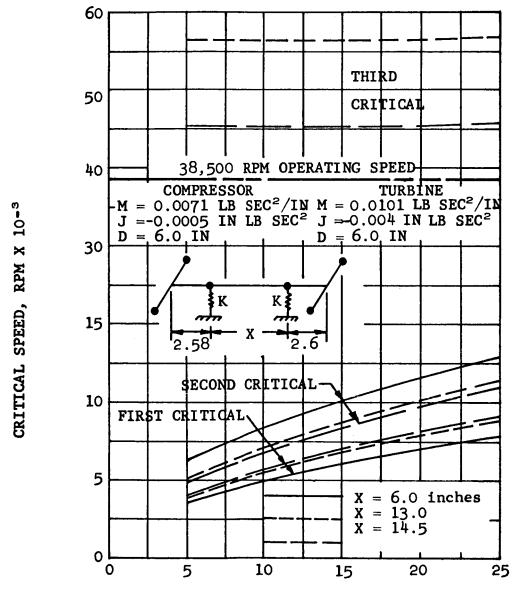
DOUBLE STRADDLE MOUNTED SYSTEM

GAS GENERATOR CONFIGURATIONS FIGURE 8

bearings tend to minimize the critical speeds and bearing loads (see Section 3.4 for a discussion of the resiliently mounted bearings). Figure 9 shows the results of the critical speed analysis. For the variable spacing and bearing combined gas film and mount spring rates, the bearing loads at design operating speed were approximately 20 pounds per 0.001 inch c.g. eccentricity (i.e., the c.g. of both the turbine and compressor masses are displaced 0.001 inch in the same direction from the rotational center). Bearing spacings from 6.0 to 13.0 inches were initially chosen to be utilized in the gas bearing testing and as limits for the gas generator. The 14.5-inch bearing spacing was rejected since the third critical speed is too close to the 38,500 rpm operating speed.

These results were obtained by utilizing an AiResearch critical-speed computer program. This program has the capability of considering gyroscopic moments, shaft flexibilities, bearing (and support) flexibilities, static and dynamic rotor unbalance, and rotor distributed properties. The rotor may be lumped into a maximum of 30 mass stations, and at each mass station the mass, polar moment of inertia, diametral moment of inertia, mass unbalance and bearing flexibility may be specified. The whirl ratio may also be prescribed. The program computes bearing loads versus speed and the rotor critical speeds and corresponding rotor modal patterns.

After the design of the gas generator was finalized, the final critical-speed analysis was accomplished, and the results are shown in Figure 10. For this analysis the bearing spacing was 7.0 inches, and the combined rotating group polar moment of inertia was 0.060 inch-lbs-sec<sup>2</sup>.

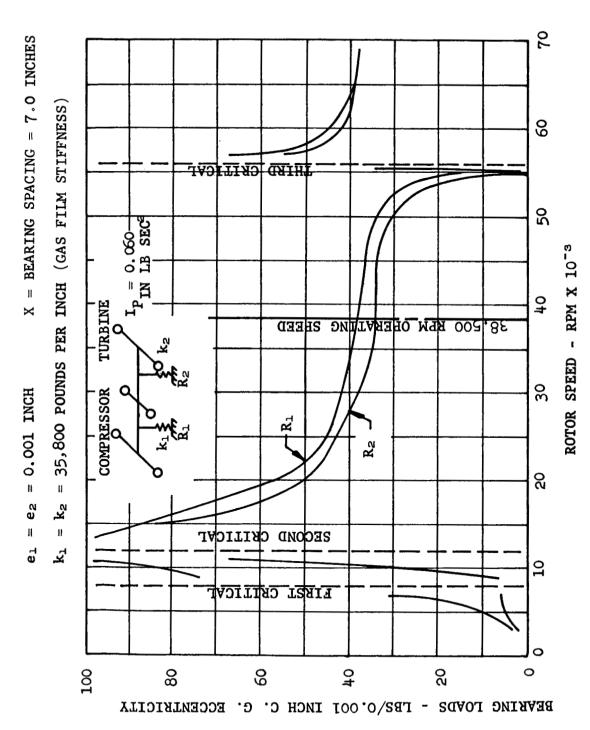


K-SPRING CONSTANT, LB/IN X 10-3

CRITICAL SPEED VS. BEARING SPRING RATE FOR NASA GAS GENERATOR, INITIAL RESULTS

FIGURE 9

Page 19



BEARING LOAD VS ROTOR SPEED
NASA GAS GENERATOR FINAL CONFIGURATION
FIGURE 10

It should be noted that the bearing loads shown in Figure 10 are for c.g. eccentricities of 0.001-inch. However, the c.g. eccentricity obtained on both the bearing test rig shafts and the gas generator is in the range of 0.0001-inch which reduces the actual bearing loads by a factor of 10.

# 3.4 Journal Gas Bearings

# 3.4.1 Design Considerations and Bearing Selection

The use of gas-lubricated bearings for the rotor support system of the gas generator is contingent upon three requirements:

- (a) that an effective means be provided to accommodate dimensional changes and misalignments of the components associated with the bearings.
- (b) that rotor dynamic stability be ensured throughout the system operating range.
- (c) that the bearings can be self-acting (use process gas) at the rotor design speed (no external pressurization available for long-time operation).

A careful review of the above requirements led to the selection of self-acting partial-arc pivoted-pad bearings. This type of bearing offers attractive mechanical design features such as the ability to accommodate rotor radial misalignments and minor bearing surface imperfections. In addition, rotor dynamic stability is, in general, considerably improved with pivoted shoe bearings as compared to other bearing types such as conventional cylindrical journal bearings.

Based on extensive turbomachinery experience with both antifiction bearings and conventional oil journal bearings, AiResearch chose to resiliently support the two journal bearing assemblies of the gas generator. The following desirable advantages are realized in the use of resilient mounts:

- (a) Rigid rotor critical speeds are influenced by resilient bearing mounts. Proper choice of the support spring rate will ensure that the first two system critical speeds are in the low-speed, low-energy regime.
- (b) Large transient rotor dynamic motions, such as occur during acceleration through system critical speeds, are not limited by the gas film thickness, since the resilient mounts will accommodate large movements.
- (c) Rotor and bearing dimensional variations as a result of thermal and centrifugal growth are partially accommodated by the deflection of the resilient mounts.
- (d) The ability to establish a positive preload on the rotor-bearing group to suppress whirl tendencies in "zero-g" environments (space power systems).

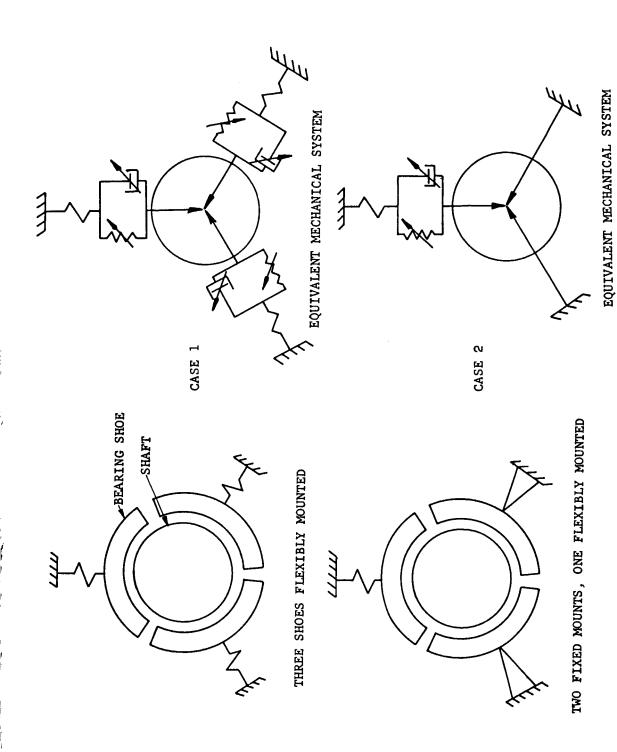
The last advantage cited--that of establishing a positive bearing preload (shoe-rotor interference at zero speed), brings about an additional design consideration of its own--that of external pressurization (a hydrostatic shoe lift-off flotation system) for starting and stopping. This combination of external pressurization during starting and stopping and self-acting ability during normal operation (no external pressurization required) eliminates the possibility of any contact between the tilting shoes of the journal bearing and the surface of the rotor.

The bearing configuration selected for the gas generator bearing development consisted of three bearing shoes, with each shoe encompassing a 100-degree arc. All the shoes were provided with pivotal freedom, and one or more of the shoes at each bearing were provided with radial resiliency. The shoes initially contacted

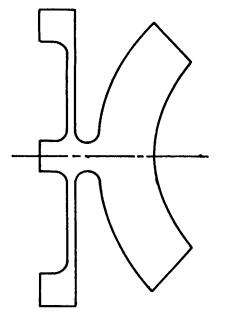
the journal with a predetermined interference load (preload) which was accommodated by the shoe resilient supports. Each shoe was lifted from the journal prior to rotation by means of hydrostatic orifices incorporated in the bearing shoe surfaces. The hydrostatic gas supply was then removed from the orifices when the shaft assembly had reached its design operating speed.

Figure 11 schematically illustrates the two resilient mounting methods that were developed. In Case 1, each of the shoes is resiliently supported, and the differential dimensional changes are accommodated by the flexibility of each of the lubricant films and of each of the three shoe supports. The equivalent mechanical system simulating this case is one of each shoe being separated from the journal by a nonlinear spring in a parallel with a nonlinear viscous damper. In this case the total film resistance acts in series with the shoe resilient support linear spring. In Case 2 of Figure 11, only one shoe at each bearing is resiliently supported, and all of the differential dimensional change is accommodated within each lubricant film and the single-shoe resilient support.

Figure 12 shows two basic bearing shoe and mount configurations that were evaluated during the testing program. Both the fixed-stem (elastically pivoted) and the ball-and-socket resiliently mounted gas bearing designs utilize the deflection of the circular plate or diaphragm to provide the mount spring rate. The inherent angular stiffness of the fixed-stem design is eliminated by the ball-and-socket design. The hydrostatic lift-off system consists of either a single orifice or four orifices incorporated into the bearing shoe surface.



BEARING MOUNTING METHODS FIGURE 11



FIXED-STEM DIAPHRAGM MOUNT

BALL-AND-SOCKET DIAPHRAGM MOUNT



FIGURE 12

## 3.4.2 Gas Bearing Analysis

Once the aerodynamic performance of the gas generator was determined (compressor impeller and turbine wheel sizes) preliminary layouts of the main rotating assembly were completed. Tentative bearing span ranges from 6.0 to 13.0 inches were obtained from these layouts. The mass and inertial properties of the aerodynamic components, and assumed rotor dimensions, including the range of bearing spans, plus a range of bearing support flexibilities, were used to determine a range of rigid-body critical speeds, as well as the third critical speed (free-free bending mode).

In general, the rotor diameter size is the governing criterion to keep the shaft free-free bending mode (third critical speed) well above the operating speed. The gas bearing journal size was therefore determined from the above analysis. The final task was to determine whether gas bearings of the prescribed diameter had adequate self-acting load-carrying ability, gas film stiffness, etc., to meet the bearing load requirements.

Analysis of the gas bearings was accomplished by a steadystate digital computer program that is capable of considering
either incompressible or compressible fluids operating in either
the laminar or turbulent flow regimes. Either a full journal or
a single sector may be prescribed with local variation in the surface geometry. In addition, provision is made for considering
local hydrostatic lift-off orifices. Thus, externally pressurized,
self-acting, or hybrid lubrication may be analyzed for a single
shoe.

An iterative numerical technique is employed to solve the Reynolds equation for finite length bearings, and, thus, end-leakage effects are implicit in the analysis. Any combination of journal dynamic motions may be considered that would introduce misalignment, journal eccentricity rate of change, and journal whirl. The program predicts bearing loads, center of pressure coordinates and moments about any specified set of coordinate axes, flow-leakage rates, and pressure distribution for a maximum matrix size of 21 rows and 36 columns.

The journal bearing computer program was utilized to formulate the initial bearing designs committed to the test program. In addition, the computer program greatly simplified the problem of evaluation of test results.

The test rotors were evolved from the aforementioned analysis. The bearing spans ranged from 6.0 to 13.0 inches. The rotors were hollow with approximately 1/4-inch wall thickness at the journals. The journal surfaces were Flame-Plated with tungsten carbide. The mass and inertial properties of each were similar to those of the future gas generator rotating assembly. For the 11-inch bearing span rotor (most frequently used in development testing), these properties were:

Mass: 0.0384 lb sec<sup>2</sup> per inch
Polar moment of inertia: 0.033 in -lb-sec<sup>2</sup>
Diametral moment of inertia: 1.271 in-lb-sec<sup>2</sup>

The pivoted-pad gas bearing/resilient-mount configurations initially analyzed and tested were:

Pivot = ball/socket and fixed-stem (elastic pivot) Mount stiffnesses = 20,000 lbs per inch and 10,000 lbs per inch Lift-off system = 4-orifice and single-orifice Clearance ratio (C/R) = 0.001 Journal radius (R) = 1.000 inch Angular span (degrees) = 100 L/R ratio = 1.5 Pivot location =  $50^{\circ}$  from leading edge

# 3.4.3 Gas Bearing Testing

Development testing of the gas bearings was accomplished on two development test rigs—the single—shoe test rig, and the dynamic two-bearing test rig. The single shoe test rig was used to investigate isolated behavior of the bearing shoe, such as hydrostatic capability, hydrodynamic performance, misalignment effects, pivotal function, shoe instability, etc., of some of the bearing designs considered in Section 3.4.3.3. The two-bearing test rig was used to evaluate complete bearing systems with the shaft oriented in the vertical plane, since this best simulated zero-g conditions for journal bearings and represented the most critical bearing operation from the standpoint of stability. All testing was undertaken in ambient air conditions, and hydrostatic supplies utilized pressurized air which could be varied from zero to 160 psig as necessary.

# 3.4.3.1 Single-Shoe Test Rig

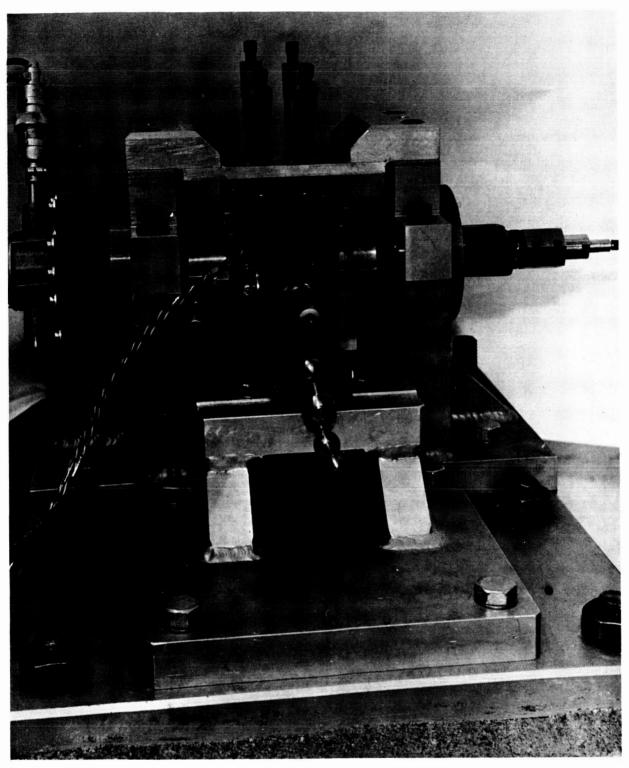
This test rig consists of a precision surface rotor mounted on precision ball bearings and driven by an air turbine. The rotor has two capacitance probes imbedded in the surface 180 degrees apart and spaced to sweep under the outer edge of each of the test shoes. Both probes are commonly connected to an axially located

junction which terminates at one end of the rotor. A spring-loaded needle brush, bearing against the rotor end, conveys the capacitance signal to a remotely located distance meter (Photocon Products Dynagage). Thus each revolution of the rotor produces two signals (sweep of each shoe edge) and gives a continuous display of the clearance between the shoe and the rotor. The test bearing shoe is mounted in a bearing carrier and loaded against the rotor. Strain gauges, mounted in a bridge circuit on the bearing resilient circular plate, are used to establish the desired initial preload, and for constantly monitoring bearing operating loads. Figure 13 shows the single shoe test rig.

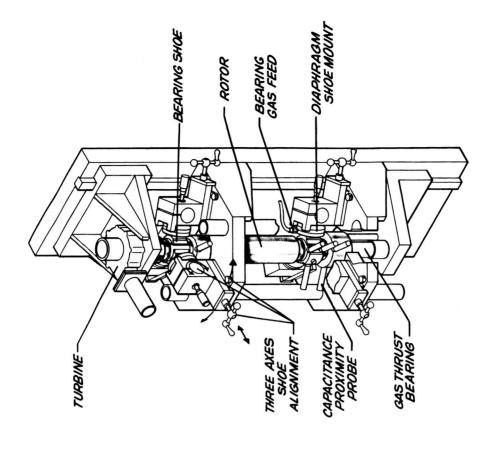
# 3.4.3.2 Dynamic Two-Bearing Test Rig

The two-bearing rotor dynamic test rig, shown in Figure 14, is used to investigate the dynamic behavior as well as other aspects of the system comprising the gas bearings and test rotor.

The test rotor is vertically supported in the test rig and is driven by a turbine wheel mounted at the rotor upper end. A hydrostatic thrust bearing supports the rotor at the bottom. Each bearing shoe assembly is secured to a support assembly. This support assembly is mounted to a track directed radially with respect to the rotor, and radial positioning of the assembly is provided by a calibrated screw thread. The track may also be pivoted about an axis parallel to the rotor axis. In addition, the support assembly has provision for pivoting of the bearing shoe assembly about a horizontal axis directed perpendicularly to the track. Thus, the angular attitude of each bearing shoe assembly may be adjusted mechanically about three orthogonal axes, and any desired initial clearance or interference between shoe and shaft may be established. A micrometer adjustment in each support assembly limits the maximum radial deflection of the bearing resilient support. Any type of resilient supporting system with any desired flexibility may be tested with this rig.



SINGLE-SHOE BEARING TEST RIG FIGURE 13



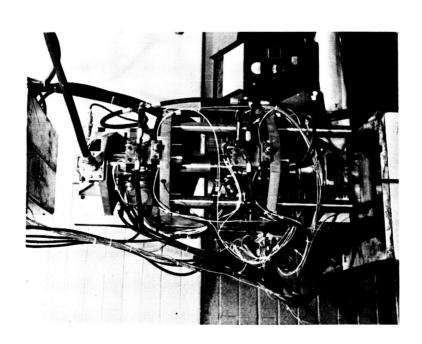


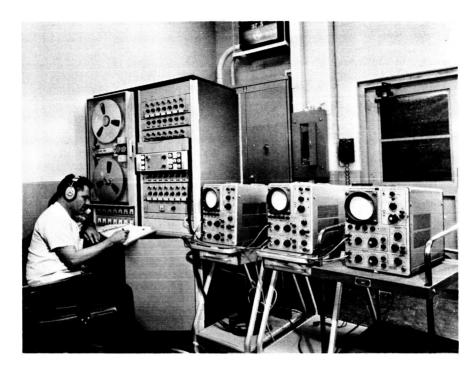
FIGURE 14

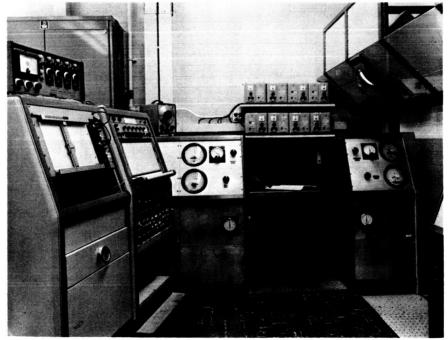
The test-rig bearing support brackets are made so that the bearing span may be varied to accommodate rotors of various lengths.

Capacitance probes (Photocons), mounted in quadrature with respect to the rotor axis on each bearing bracket, monitor shaft dynamic motions in the radial direction near each bearing. In addition, the relative motions of one bearing shoe are monitored by two capacitance probes directed at the upper and lower regions of the shoe leading edge, and also by a third Photocon directed at the shoe trailing edge, thus providing the capability of describing the motion of the shoe in the two planes of pitch and roll. A Photocon at the bottom of the rotor measures the axial motions of the rotor. This instrumentation, as well as speed output, is connected to a 14-channel magnetic tape recorder (see Figure 15 for the bearing test facility instrumentation), thus providing a means of recording the continuous history of test runs from start-up to full speed.

For each test, initial alignment of each bearing shoe may be obtained with the test rotor supported on alignment center pins at each end. After alignment is achieved, the center pins are removed, and the hydrostatic thrust bearing is replaced at the bottom of the shaft. Strain gauges cemented to each bearing shoe resilient plate are calibrated as functions of both linear and angular displacements of the bearing. The outputs from each of these strain gauges are utilized as the basis of establishing the desired radial alignment and initial preload between the bearing and the shaft.

These strain-gauge signals are also utilized to continuously monitor bearing loads during testing. Thermocouples connected to the bearing shoes are used to determine nominal shoe temperature, and signals from the thermocouples and strain gauges are continuously recorded on a Sanborn recorder.





GAS-BEARING TEST FACILITY INSTRUMENTATION FIGURE 15

## 3.4.3.3 Test Results

As previously noted on page 29, the four basic pivoted-pad gas bearing configurations initially tested were (in order):

- (1) Fixed-stem, four-orifice
- (2) Ball-and-socket, four-orifice
- (3) Fixed-stem, single-orifice
- (4) Ball-and-socket, single-orifice

Each of the above bearing configurations utilized the equal spring mount system shown in Figure 11, Case 1.

The tests of the first bearing configuration (fixed stem, four orifice) were satisfactory and rotor speeds to 50,000 rpm were accomplished without incident. These tests established that a bearing of this type might meet the operating requirements. However, initial alignment problems inherent in the fixed-stem design led to further testing, the goal being to develop a workable ball-and-socket pivot design to alleviate the bearing alignment problems in the final gas generator. Test evaluation of the remaining three configurations indicated that a shoe geometry change was required to provide a wide range of stable rotor operation in the externally pressurized, hybrid, and self-acting bearing regimes. Some of the problems encountered in these tests were shoe flutter and spragging (shoe leading-edge dip).

Results of computer analyses showed that an increase in the shoe clearance ratio and a relocation of the shoe pivot point would tend to optimize the shoe stability characteristics and also provide a reduction in the predicted shoe friction loss.

Based on this information, the bearing shoes were redesigned (both fixed-stem and ball-and-socket types) with the pivot located 65 percent back from the shoe leading edge and the clearance ratio (C/R) increased to 0.0017. Testing of these configurations with the equal spring mount system proved to be satisfactory. The shoe flutter and spragging mentioned above were no longer a problem. The spring rate of this particular system was in the order of 20,000 pounds per inch. In order to decrease the mount spring rate, the mounting system depicted in Figure 11, Case 2 was used (two fixed shoes per bearing and one resilient mount). The composite spring rate of this system was in the order of 5,400 to 6,000 pounds per inch. The stability of this system was excellent, and in addition, the low composite spring rate afforded adequate rotor thermal and centrifugal growth relief.

## 3.4.4 Gas Generator Journal Bearing Configuration

As a result of the testing discussed above, the gas generator bearing configuration selected was based on a similarity of the bearing compressibility number,  $\lambda$ , between the gas generator bearing and the air test bearings where

$$\lambda = \frac{6\mu\Omega}{P_a} \left(\frac{R}{C}\right)^2$$

 $\mu$  = lubricant viscosity, lbs per sec per sq inch

R = journal radius, inches

 $\Omega$  = angular velocity, radians per second

 $\mathbf{P_a}$  = ambient pressure, psia

c = bearing clearance (difference between bearing and journal radii), inches

 $\lambda$  = bearing number

For the gas generator with a design lambda  $(\lambda) \approx 1.5$ , the journal bearing configuration was thus determined to be:

Journal radius, inches = 0.875

Clearance ratio = 0.00263

L/R ratio = 1.50

Angular span, degrees = 100

Pivot location (from leading edge), degrees = 65

Pivot type: Ball-and-socket

Mounting system: Two shoes per bearing radially

constrained, the third shoe resiliently supported by a 2,500-pound-

per-inch diaphragm mount

Number of hydrostatic supply orifices per

shoe: Four

These characteristic requirements are based on the machine design point of 38,500 rpm shaft speed, 12 psia journal ambient pressure, argon gas atmosphere, and a journal ambient temperature level of  $500^{\circ}F$ .

The four hydrostatic orifices provide easier lift-off action and are utilized instead of the single orifice so that the orifices are located away from the point of peak hydrodynamic pressure.

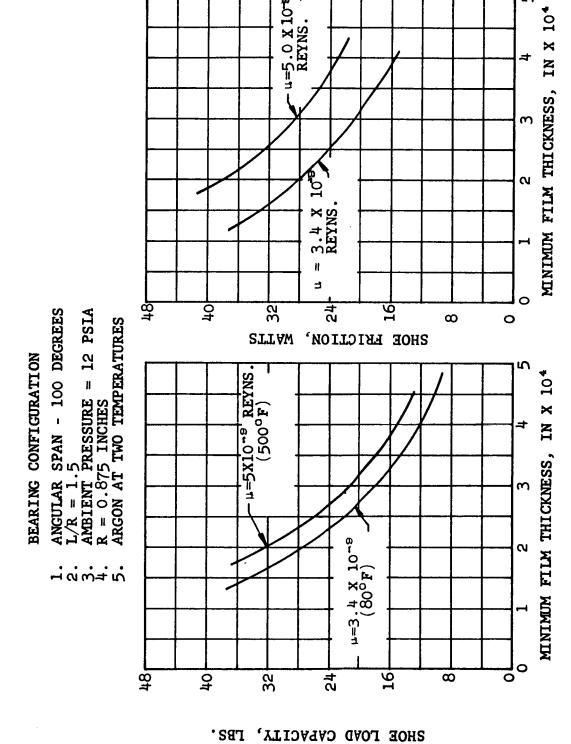
Figure 16 shows the predicted performance of the bearings at the design conditions.

# 3.5 Thrust Gas Bearings

# 3.5.1 Thrust Bearing Design

The design of the thrust bearing was based on the following calculated gas generator operating requirements when operating in the design system:

- (a) A maximum start-up thrust load to self-sustained speed of 60 pounds in a direction from the compressor to the turbine (with a turbine back pressure of 3 psia assumed).
- (b) At self-sustained speed (approximately 21,000 rpm), the thrust direction reverses and its magnitude becomes approximately 20 pounds.
- (c) The thrust load increases from 20 pounds to a maximum value of 30 pounds at operating speed, in a direction from the turbine to the compressor. The normal thrust bearing is to operate hydrodynamically, beginning at self-sustained speed.

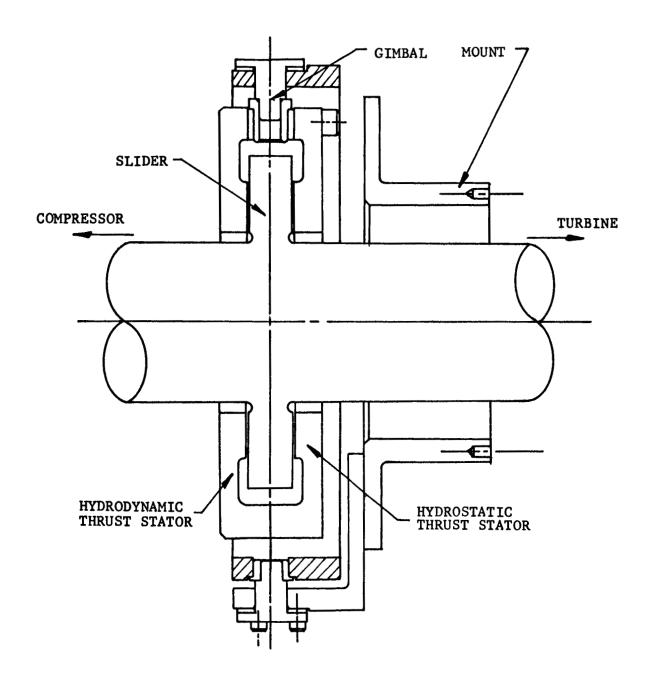


PREDICTION OF GAS GENERATOR JOURNAL BEARING
PERFORMANCE AT DESIGN SPEED
FIGURE 16

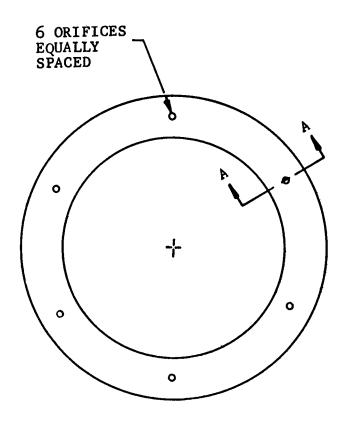
- (d) The bearing is to use argon as the lubricant, with the temperature in the range of 200°F to 800°F.
- (e) Ambient pressure range in the bearing cavity is assumed to vary from 5 psia to 12.0 psia.

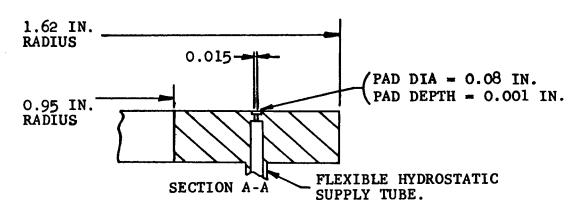
Figure 17 shows the double-sided thrust bearing design. The rotor slider is enclosed by two elements; the hydrodynamic bearing is on the compressor side, and the hydrostatic bearing is on the turbine side. The two thrust stators are tied together and supported by a gimbal that allows rotation of the stators in the plane of the slider. Figures 18 and 19 schematically show the hydrostatic and hydrodynamic thrust stators. The hydrostatic stator incorporates six orifices for the hydrostatic lift-off and operation during "reverse" thrust conditions (prior to selfsustained speeds). To facilitate start-up, four hydrostatic orificed pads have been incorporated in the hydrodynamic bearing surface to ensure an adequate operating clearance between the slider and the hydrodynamic bearing, thus precluding rubbing of these bearing surfaces.

By use of a computer program, studies were conducted on the normal thrust bearing to determine an optimum hydrodynamic bearing size based on load capacity and thrust bearing friction at the design operating conditions. Results of this analysis indicated that the thrust bearing surfaces should have an outside radius of 1.62 inches and an inside radius of 0.95 inch. Figures 20,21, and 22 show the hydrostatic and hydrodynamic performance of the thrust bearings.

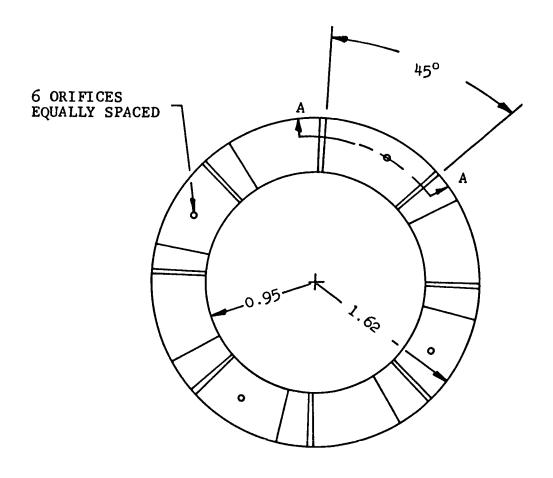


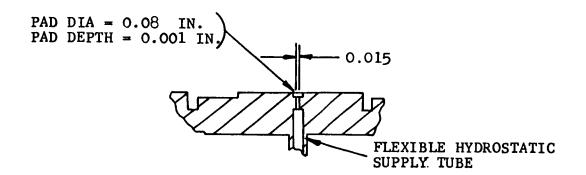
THRUST BEARING AND GIMBAL ASSEMBLY
FIGURE 17



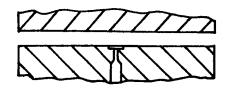


# HYDROSTATIC THRUST BEARING FOR NASA GAS GENERATOR





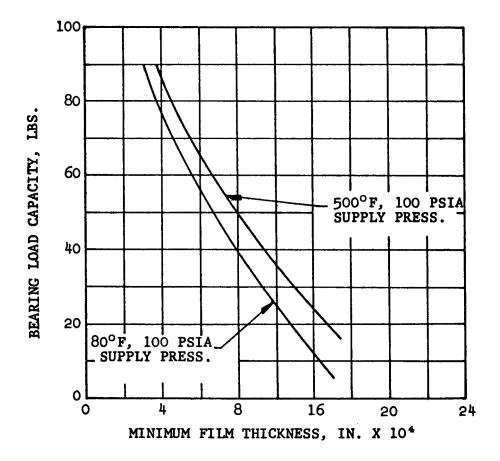
HYDRODYNAMIC THRUST BEARING FOR NASA GAS GENERATOR
FIGURE 19



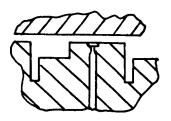
#### HYDROSTATIC STATOR CROSS-SECTION

#### BEARING CONFIGURATION

- 1. OUTER RADIUS = 1.62 INCHES
- INNER RADIUS = 0.95 INCH AMBIENT PRESSURE = 12 PSIA 2.
- ARGON LUBRICANT



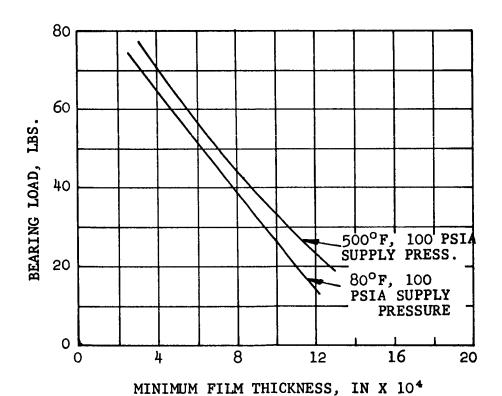
HYDROSTATIC THRUST BEARING LOAD CAPACITY FIGURE 20



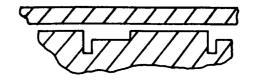
# HYDRODYNAMIC THRUST BEARING CROSS-SECTION

### BEARING CONFIGURATION

- OUTER BEARING RADIUS = 1.62 INCHES 1.
- INNER BEARING RADIUS = 0.95 INCHES 2.
- AMBIENT PRESSURE = 12 PSIA
- 3. 4. FOUR OF 8 PADS PROVIDED WITH EXTERNAL PRESSURIZATION ORIFICES
- ARGON LUBRICANT 5.



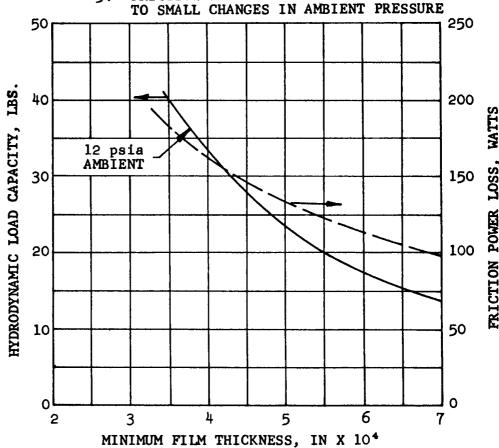
HYDRODYNAMIC THRUST BEARING, HYDROSTATIC LOAD CAPACITY



#### HYDRODYNAMIC STATOR CROSS-SECTION

#### BEARING CONFIGURATION

- 1. ARGON LUBRICANT, 500°F, u=5X10°8
- 2. SHAFT SPEED = 38,500 RPM
- 3. THRUST SURFACES ASSUMED PLANE, NO THERMAL DISTORTION CONSIDERED
- 4. OUTSIDE PAD RADIUS = 1.62 INCHES
- INSIDE PAD RADIUS = 0.95 INCH
  5. FRICTION POWER GENERATED IS INSENSITIVE
  TO SMALL CHANGES IN AMBLENT PRESSURE



NASA GAS GENERATOR HYDRODYNAMIC THRUST BEARING PERFORMANCE

## 3.5.2 Thrust Bearing Tests

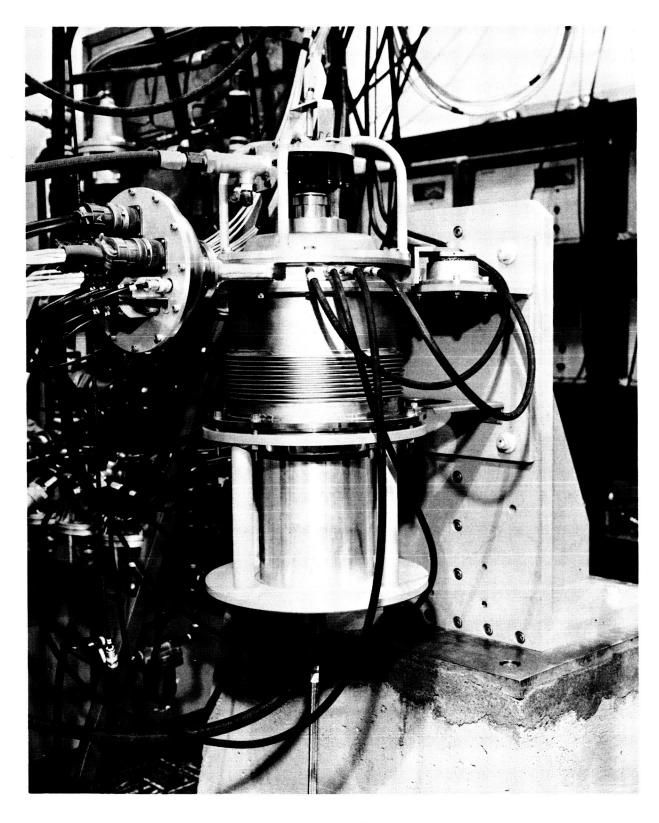
# 3.5.2.1 Thrust Bearing Integration Test Rig

The integration of the thrust-bearing/gimbal-mount assembly and journal bearings was accomplished on a bearing test rig that very closely simulates the final gas generator design. The rig consists of a housing, bearing carriers, journal gas bearings, and shaft that exactly duplicate the final gas generator configurations. Dummy masses are included on the shaft to simulate the masses of the journal and turbine wheels. An air turbine motor is utilized to drive the shaft. Loading of the thrust bearing can be varied by introducing a positive or negative pressure in a cavity under the shaft. The test-rig instrumentation is similar to the final gas-generator instrumentation. Figure 23 shows the bearing test rig as installed in the bearing test facility.

# 3.5.2.2 <u>Thrust Bearing Integration Tests</u>

Various gimbal configurations were tested with varying degrees of success. The configuration that ultimately proved to be the most successful -- and the one which was incorporated into the gas generator -- utilized two pairs of pin-in-socket pivots, each pair located in the mean plane of the thrust surfaces.

Stable operation was obtained on both thrust surfaces, and thrust transfers between the thrust surfaces were very satisfactory. Loads up to 80 pounds were achieved on the reverse thrust bearing (hydrostatically). Loads from 0 to 35 pounds and 5 to 28 pounds were achieved on the normal thrust surface operating hydrostatically and hydrodynamically, respectively. These tests, undertaken on the frame test rig, were considered to have demonstrated that integration of the journal and thrust bearings had been achieved.



COMPANY-SPONSORED BEARING TEST RIG FIGURE 23

## 3.6 Thermal Analysis

A digital computer thermal analysis program is the only economical means by which an integrated housing, rotating group/ bearing assembly can be analyzed from a thermal standpoint to determine:

- (a) Operating temperatures throughout the machine
- (b) Relative parts movements
- (c) Thermally induced stresses
- (d) Material requirements
- (e) Cooling flows if required
- (f) Bearing operating requirements

Thermal analyses are conducted at AiResearch with digital computer programs by mathematically defining the complete turbomachine together with the inlet and discharge design conditions, bearing frictional power losses, bearing hydrostatic gas supply flow, and various cooling flow rates, etc. Information necessary for the thermal analyses is the basic machine configuration as defined by the preliminary layout; the wheel configuration as defined by the stress and aerodynamic analyses; and the bearing spacing, bearing initial configuration, and power losses as defined by the dynamic and bearing analyses.

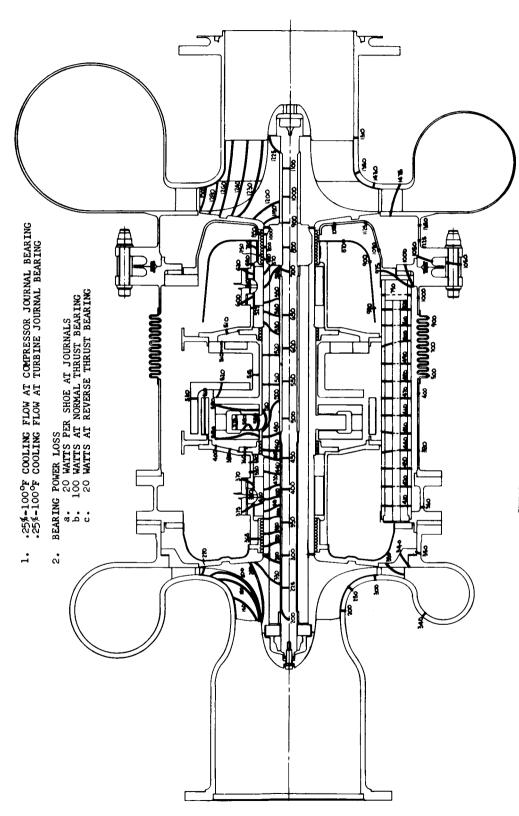
Materials for the various component parts are selected from an initial thermal analysis, and cooling flows are selected, if required. The analysis is then performed again with the configuration modifications until bearing temperatures and thermal gradients are reduced to within acceptable bearing design, stress, and growth limitations.

A thermal analysis by use of the method discussed above was conducted on the basic gas generator and the steady-state temperature results are shown in Figure 24.

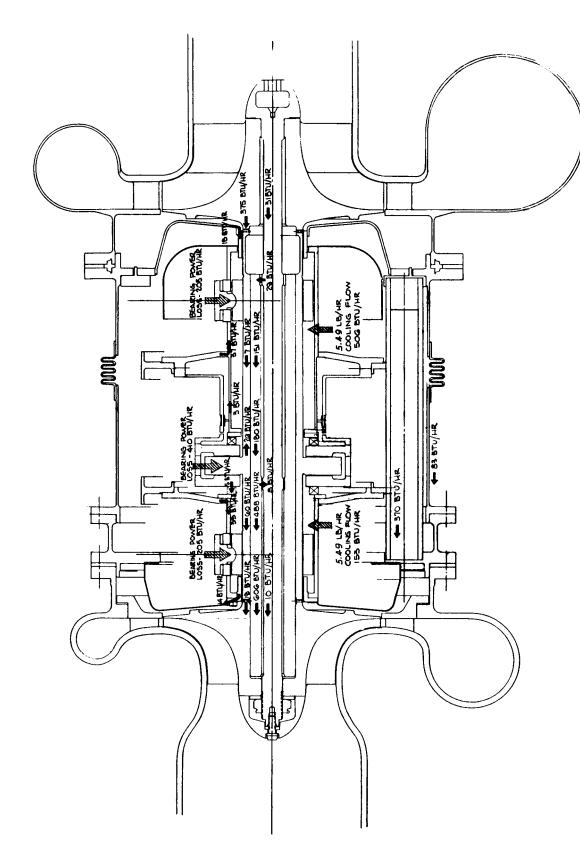
Figure 25 illustrates the heat flow paths and the quantities of heat energy being transferred through the rotor and associated parts in the gas generator. It may be noted that approximately 50 percent of the heat input to the shaft is convected away by the cooling gas. The remaining 50 percent is conducted to the impeller where it is convected to the compressor through-flow. Figure 26 presents the gas generator's shaft temperature distribution at steady state and at three values of time during the start-up transient.

Figure 27 presents the transient and steady-state compressor and turbine axial shroud clearances. With initial shroud clearance settings of 0.012 and 0.014 inch for the compressor and turbine, respectively, steady-state running clearances of approximately 0.010 inch will be achieved. During transient operation the shroud clearances open up to a maximum of 0.017 and 0.020 inch for the compressor and turbine, respectively.

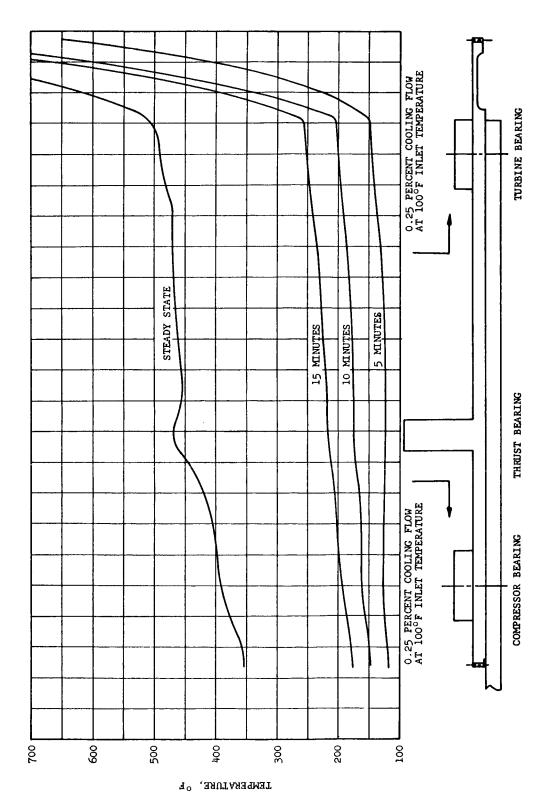
Figure 28 presents the temperature distribution at the bearing shoe and the adjacent journal area, for the compressor and turbine bearings, respectively, at steady state and at three time points during the transient. These illustrate how closely in temperature level the shoes and the journals follow each other and that they are relatively free from coning and crowning.



STEADY STATE TEMPERATURE DISTRIBUTION



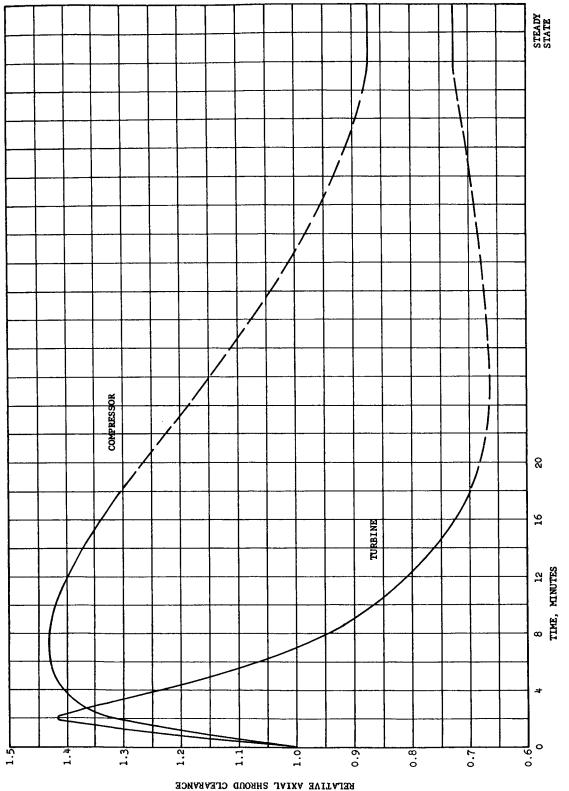
HEAT FLOW DIAGRAM FIGURE 25



SHAFT TEMPERATURES AT DIFFERENT VALUES OF TIME

53





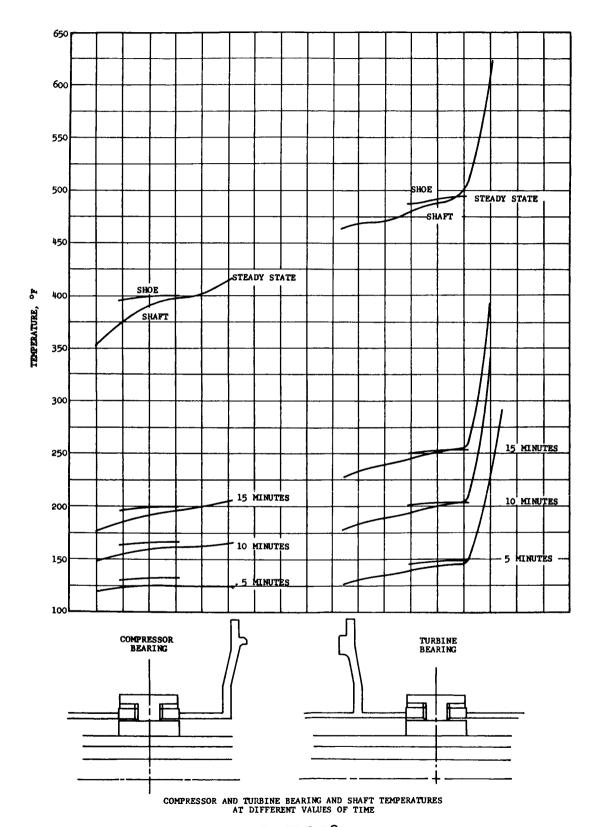


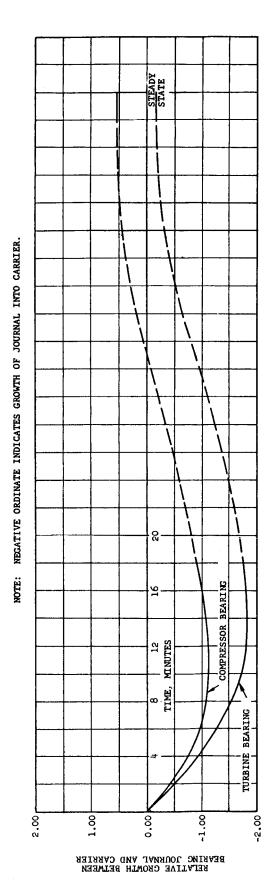
FIGURE 28

Figure 29 presents the transient and steady-state relative movement between the bearing journals and the bearing carriers. Relative parts movement for the gas generator is in the order of 0.001 inch and must be accommodated by the resiliently mounted gas bearings.

Figure 30 presents the transient and steady-state position of the mass center lines of the journals relative to the geometric center line of the shaft was initially displaced 0.002 inch relative to the geometric center line of the shrouds. Hence, the gas generator must be assembled with the shaft intentionally displaced approximately 0.002 inch, relative to the shrouds, in the direction opposite to the spring mount. This will give, as Figure 30 indicates, a maximum shift of centers of 0.002 and a steady-state running position that is nearly centered in the shrouds.

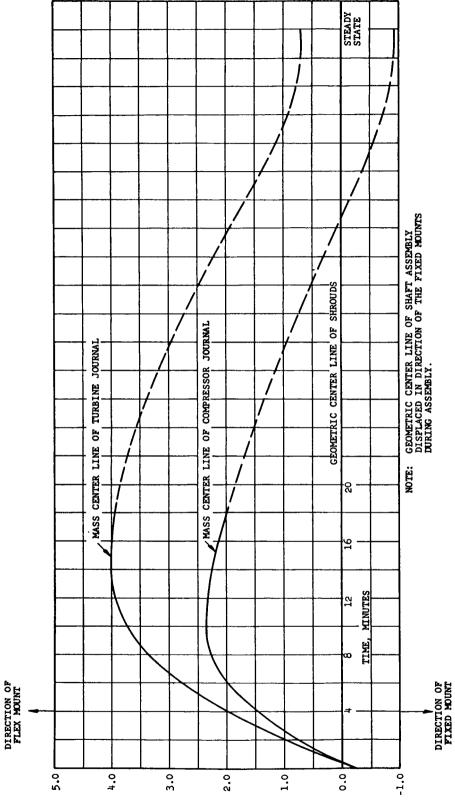
Figure 31 shows the transient and steady-state loads imposed on the compressor and turbine journal bearings. Effects considered in the load analysis were centrifugal growth, unbalance, relative thermal growth, and film thickness variation with load and ambient temperatures. An initial preload of 10 pounds and a rotor unbalance of 0.0002 c.g. eccentricity were assumed, and a spring rate of 1,500 pounds per inch was selected for the single, flexibly mounted bearing. For the thermally induced changes predicted by the gas generator thermal analysis, reasonable bearing loads and load transients exist with the gas generator design.

Figure 32 presents transient and steady-state temperatures for several representative points located throughout the gas generator. Points such as the turbine nozzle, the turbine wheel hub, and the diffuser vane react rather quickly, reaching their steady-state temperatures in a matter of a few minutes. Other



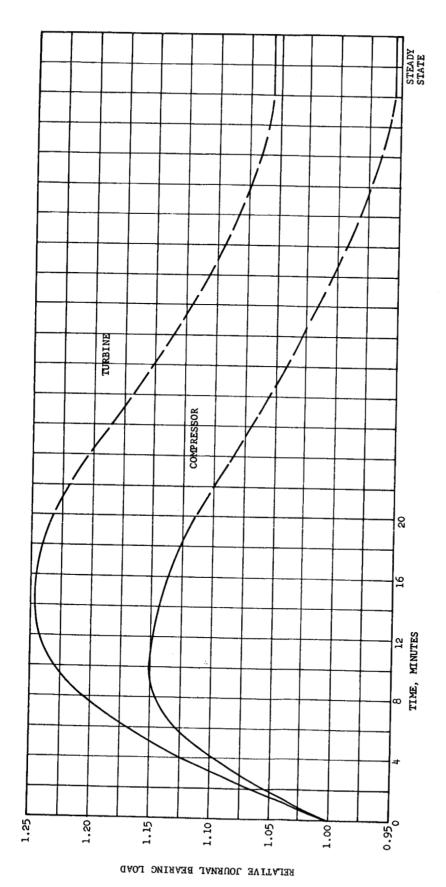
TRANSIENT AND STEADY-STATE BEARING JOURNAL TO CARRIER RELATIVE EXPANSION

FIGURE 29



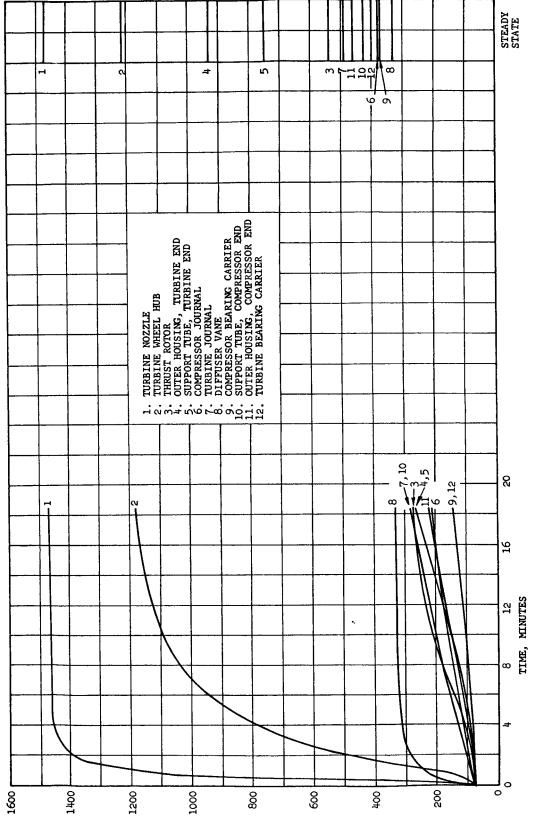
TRANSIENT AND STEADY STATE OF THE MASS CENTER LINE OF THE SHAFT

RELATIVE SHAFT MASS CENTER LINE POSITION



TRANSIENT AND STEADY-STATE JOURNAL BEARING LOADS

FIGURE 31



TRANSIENT AND STEADY-STATE TEMPERATURES OF REPRESENTATIVE POINTS IN THE GAS GENERATOR FIGURE 32

TEMPERATURE, °F

points such as those in the support structure and bearing carrier take an unpredictably long time to reach steady state.

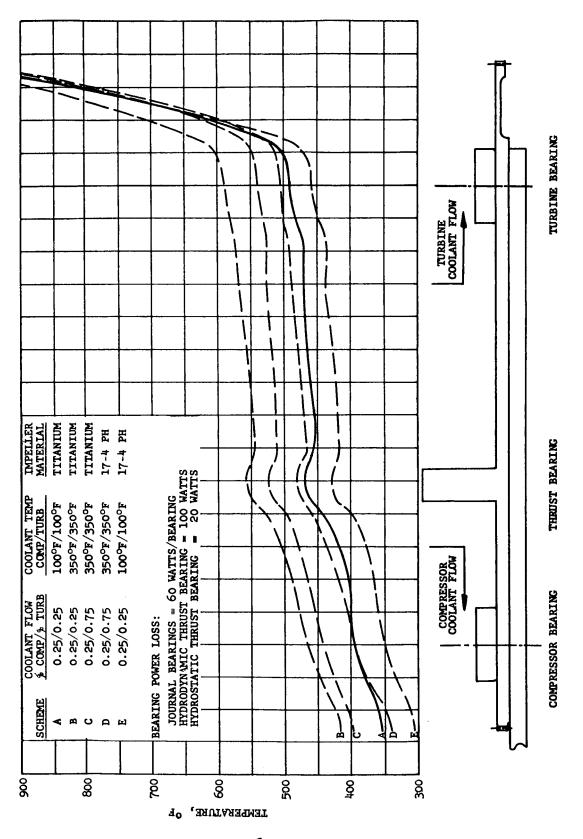
During the course of the thermal analysis, several combinations of coolant flow rates and coolant initial temperatures were investigated in an attempt to determine if there were any optimum combination. Figure 33 presents four of the many schemes investigated. These four, shown in dashed lines, are compared to the final design, indicated by the solid line, all using identical hardware. The accompanying table lists all the particulars of each scheme and presents the steady-state values of relative expansion between the bearing carrier and the journals for each scheme. In all instances the relative expansions are well within the capability limits of the gas generator final design. It appears that there should be no concern about choosing a cooling arrangement for its own sake, because of the relative freedom to base the selection on overall system performance and/or complexity.

Cooling scheme "A" was therefore selected, since, with the labyrinth seals at their minimum clearance, the seals could be opened up to increase the cooling flow during evaluation testing by the NASA.

# 3.7 Shock and Vibration Analysis

For the shock and vibration analysis of the gas generator, the system analyzed consisted of three bodies defined as follows:

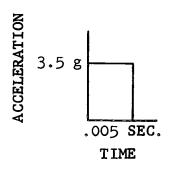
- Body 1 Large mass representative of the launch vehicle structure
- Body 2 Gas-generator housing
- Body 3 Gas-generator rotating assembly



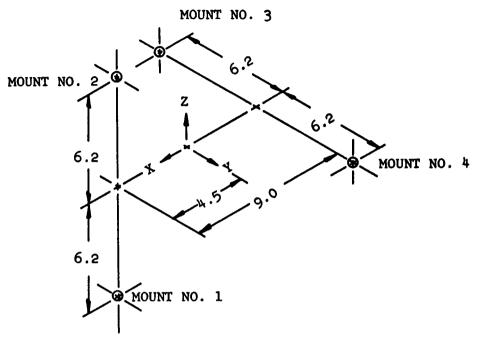
STEADY-STATE SHAFT TEMPERATURES FOR VARIOUS COOLING SCHEMES FIGURE 33

The gas generator is isolated from the launch vehicle so that the acceleration and displacement imposed are within acceptable limits.

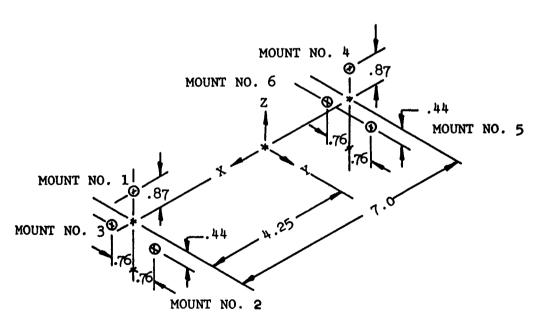
Figures 34 and 35 are schematics of the mount locations used in the design analysis, and Table 2 shows the spring rates of the mounts for each body during launch. It should be noted that, to have a complete analysis of the system, additional information would be required concerning the ducts to be attached to the gas generator. During launch the minimum vibratory frequency to be isolated is 61 cps. The gas-generator mounts should be designed to have a spring rate that will provide a natural frequency below 16 cps. This places the system resonant condition in a region of impressed frequency of relatively low input acceleration. By using the spring rates listed in Table 2, the natural frequency of the system is found to be 13.7 cps. This result is for an impressed acceleration in the Z direction shown below.



With the same impressed acceleration in both the X and the Z directions, the resulting loads are as shown in Tables 3 and 4. Note that the loads for Body 2 (97 pounds in weight) and Body 3 (15.5 pounds in weight) show that the 3.5-g impressed acceleration is effectively isolated. Figure 36 shows a shear and bending moment diagram for the Z direction shock application.



SCHEMATIC OF GAS GENERATOR FRAME MOUNT POINTS (BODY 2) FIGURE 34



SCHEMATIC OF GAS GENERATOR SHAFT MOUNT POINTS (BODY 3)

TABLE 2
SUMMARY OF SPRING RATES FOR LAUNCH CONDITION

K = LBS/INCH	BODY 2				BODY 3						
MOUNT SPRING RATE	1	5	3	4	1	2	3	14	5	6	
K <sub>x</sub>	65.0	65.0	650.0	650.0	10 <sup>6</sup>	0	0	10 <sup>8</sup>	0	0	
Ку	650.0	65.0	65.0	650.0	0	5(10)5	5(10)5	0	5(10)5	5(10)5	
K	65.0	650.0	650.0	650.0	3(10)3	5(10)5	5(10)5	3(10)3	5(10)5	5(10) <sup>3</sup>	

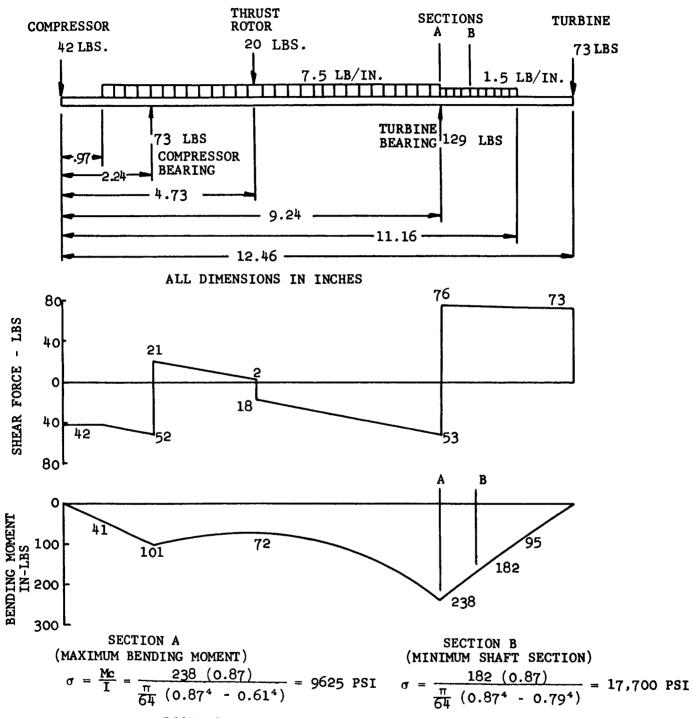
TABLE 3

SUMMARY OF MAXIMUM FORCES AT MOUNTS
FOR RECTANGULAR SHOCK PULSE IN
X DIRECTION DURING LAUNCH CONDITION

F = LBS	BODY 2				BODY 3						
FORCE	1	2	3	4	1.	2	3	4	5	6	
F <sub>x</sub>	-48.6	-48.6	-485.6	-485.6	-92.2	0	0	-92.2	0	0	
Fy	0	0	0	0	0	0	0	0	0	0	
F	0	0	0	0	.1	10.9	10.9	0	-10.6	-10.6	

TABLE 4
SUMMARY OF MAXIMUM FORCES AT MOUNTS
FOR RECTANGULAR SHOCK PULSE IN
Z DIRECTION DURING LAUNCH CONDITION

F = LBS	BODY 2				BODY 3						
FORCE	1	> 2	3	4	1	2	3	4	5	6	
F <sub>x</sub>	9.9	-9.9	0	0	3	0	0	3	0	0	
F <sub>v</sub>	0	0	0	0	0	0	0	0	0	0	
Fz	-46.4	-466	-324.4	-324.4	2	-36.5	-36.5	4	-64.4	-64.4	



LOAD, SHEAR, AND BENDING MOMENT DIAGRAM FOR RECTANGULAR SHOCK PULSE IN Z DIRECTION DURING LAUNCH CONDITION

With the mount system that has been designed, the vibration frequencies that can cause the most damage have been isolated. The mount system also effectively reduces the acceleration transmitted through the mounts to the gas generator housing and rotating assembly.

# 3.8 <u>Instrumentation</u>

During the journal and thrust bearing testing, the instrumentation incorporated in the bearing test rigs (described in Section 3.4) was found to be very useful for setting up the bearings and determining the bearing performance. Bearing and shaft stability was monitored with capacitance probes. Bearing loads were determined and monitored with strain gauges. Thermocouples were utilized to determine bearing temperatures as well as the other instrumentation component temperatures for calibration purposes.

Based on the instrumentation utilized during the bearing testing, the instrumentation required to monitor the operation of the gas generator was analyzed and the requirements were determined as follows:

- (a) Rotor shaft position at both the turbine and compressor journals, with proximity probes in quadrature (four probes required).
- (b) Thrust bearing gas film thickness, with the use of proximity probes on the hydrostatic and hydrodynamic thrust faces (two probes required).
- (c) Journal bearing shoe loads, with strain gauges used on the two flexible diaphragm mounts (eight gauges required).

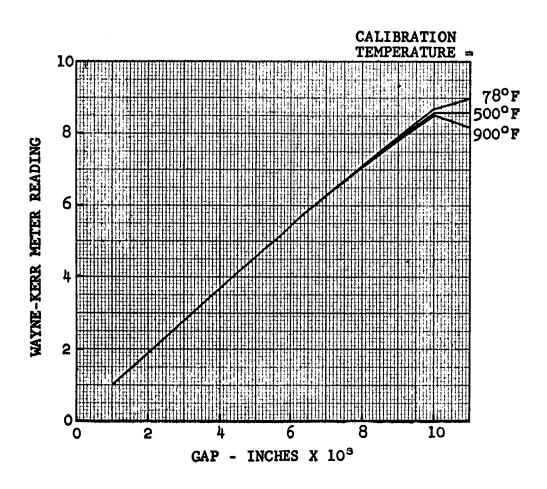
- (d) Thrust bearing loads, with strain gauges used on the bearing mount (four strain gauges required).
- (e) Thermocouples monitoring temperatures within the machine (54 thermocouples required).
- (f) Shaft speed, with three electronic speed pickups used in the same shaft plane (three required).
- (g) Static pressure taps on the turbine scroll assembly (two required).
- (h) Static pressure taps within the machine (two required for bearing labyrinths and one required for the cavity).

### 3.8.1 Capacitance Probes

Since commercially available proximity probes were not available, the required probes were purchased from the AiResearch Instrumentation Laboratory.

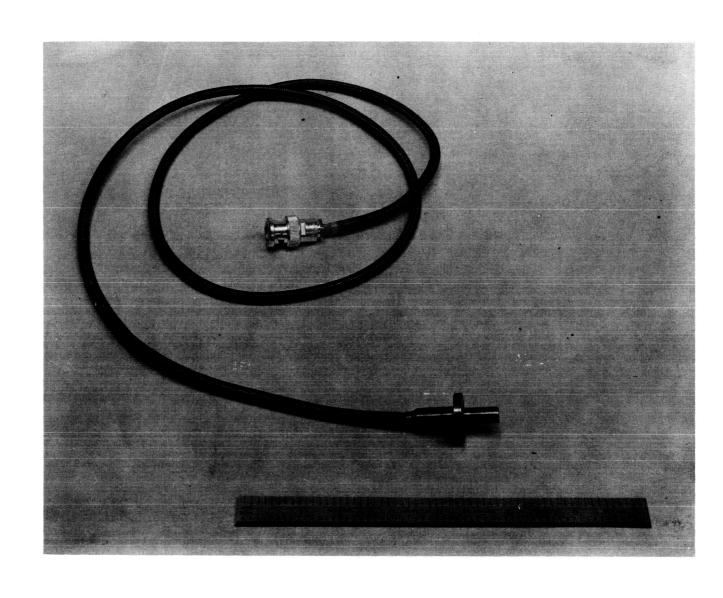
Tests on the completed gas-generator capacitance probes were performed and the results are summarized below:

- (a) Structural integrity is more than adequate for the operating range of temperatures within the gas generator.
- (b) Insulation resistance is fully compatible with the equipment to be used for readout purposes.
- (c) Calibration of the probes showed good linearity with acceptable temperature characteristics. Representative data is shown in Figure 37 for a flat-plate calibration. A complete probe assembly is shown in Figure 38.



TEST RESULTS ON PROXIMITY PROBE CALIBRATIONS

FIGURE 37



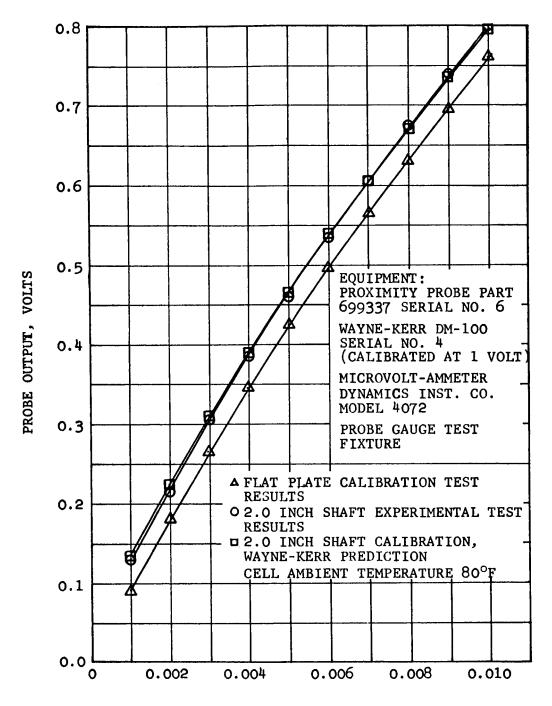
SHAFT CAPACITANCE PROBE FIGURE 38

The test to determine the effect of a curved surface upon the calibration of a proximity probe showed that excellent correlation is obtainable between actual test results and Wayne-Kerr's predictions for similar probes. Figure 39 shows the test results obtained under normal ambient test conditions. The total variation between actual and predicted values is within ±1/2 percent of full scale. Wayne-Kerr's correction factor can therefore be applied to the flat-plate probe calibration for shaft diameters of the order of 2.00 inches. Figure 40 shows the test probe mounted in the calibration fixture, the curved surface representative of a 2.00-inch-diameter shaft, and the use of gauge-blocks to accurately set the probe gaps.

### 3.8.2 Strain Gauges

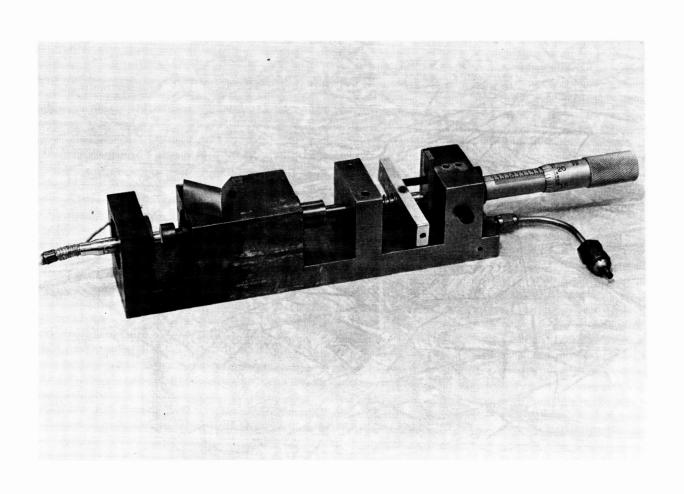
An experimental investigation was performed early in the program to establish whether or not four SR-4 strain gauges, mounted in quadrature on the plate surface, had sufficient sensitivity to indicate bearing load, bearing misalignment, and direction of bearing misalignment. Two prototype diaphragm mounts were instrumented, the diaphragms loaded in 5-pound increments, and the deflection recorded as a function of load. The angular stiffness of the diaphragm was determined by applying a moment at the plate center and measuring the angular deflection of the plate center.

The test results indicated that the strain gauge method for measuring bearing shoe load and angular misalignment has adequate sensitivity and provides a powerful tool for assisting in the aligning of the bearings, setting bearing preload, and measuring bearing loads during transient and steady-state operation.



PROBE GAP, INCHES

PREDICTED AND ACTUAL TEST RESULTS OF EFFECT OF CURVED SURFACE ON FLAT-PLATE CALIBRATION OF WAYNE-PERR PROXIMITY PROBE SYSTEM



PROXIMITY PROBE IN CALIBRATION FIXTURE FIGURE 40

The utilization of strain gauges on the thrust bearing mount to determine thrust loading is similar to journal bearing use.

The three strain-gauge circuits comprise the conventional four-arm bridge network, with two opposite arms of the bridge being subjected to the readout system's excitation signal and the two remaining arms reading the output signal. A representation of the turbine-end shoe diaphragm circuit is shown in Figure 41.

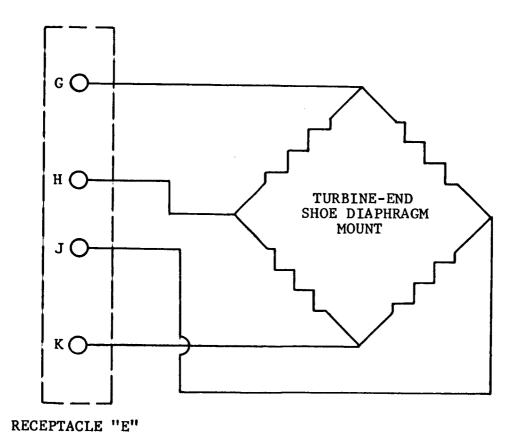
The compressor-end shoe diaphragm circuit and thrust bearing load-sensing circuit are to be handled in a like manner. Calibrations of the strain gauges were provided with the final gas generator.

### 3.8.3 Thermocouples

A total of 54 points were instrumented on the basis of the thermal analysis undertaken during the design phase of the program. However, 23 thermocouples were hooked up to the instrumentation receptacle plate for readout during the acceptance tests, as discussed in Section 5.0. The remaining 31 thermocouples were included since the incorporation of additional thermocouples would necessitate the complete disassembly of the gas generator at the NASA, thus resulting in possible delays during the subsequent testing program.

# 3.8.4 Additional Instrumentation

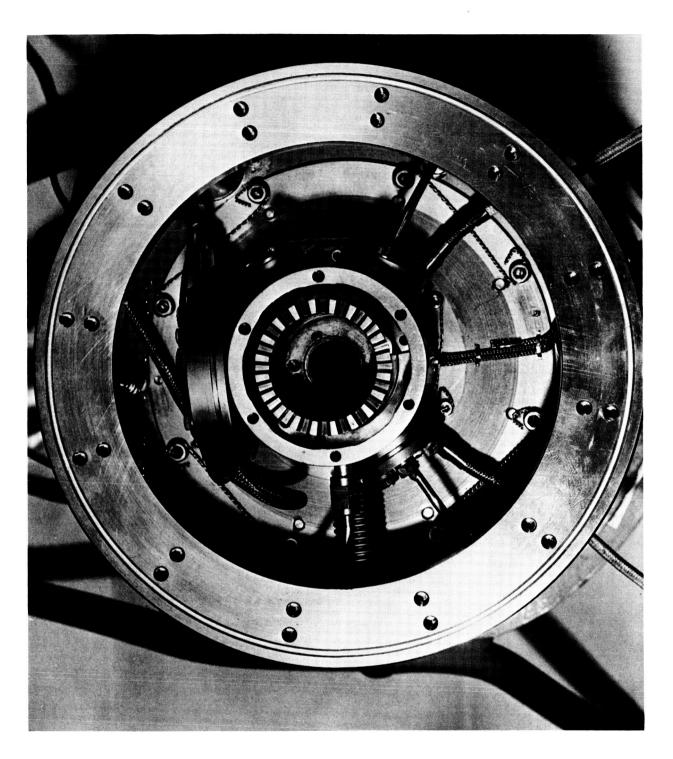
Figure 42 shows one of the magnetic speed pickups, three of which are incorporated into the gas generator. Figures 43, 44, 45, and 46 show the installation of the instrumentation prior to the acceptance test. The instrumentation leads are hooked to the instrumentation receptacle plate shown in Figure 47.



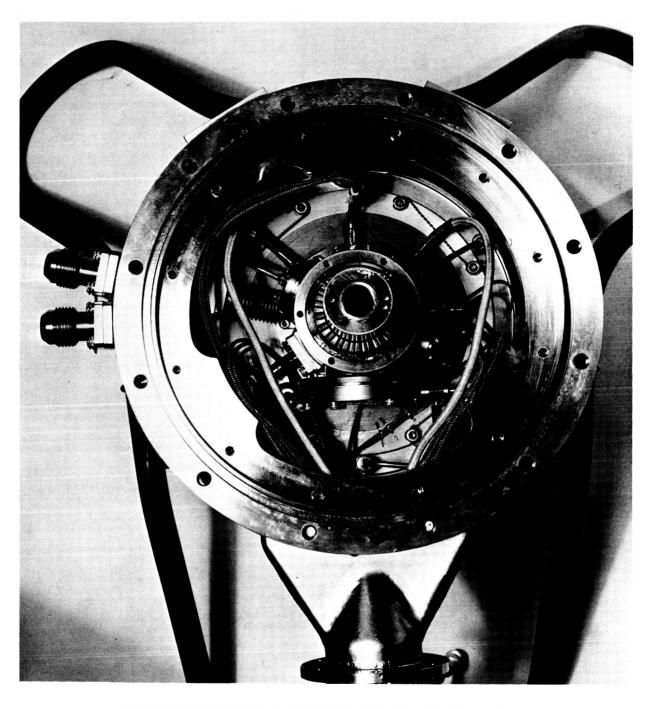
REPRESENTATIVE STRAIN-GAUGE CIRCUIT
FIGURE 41



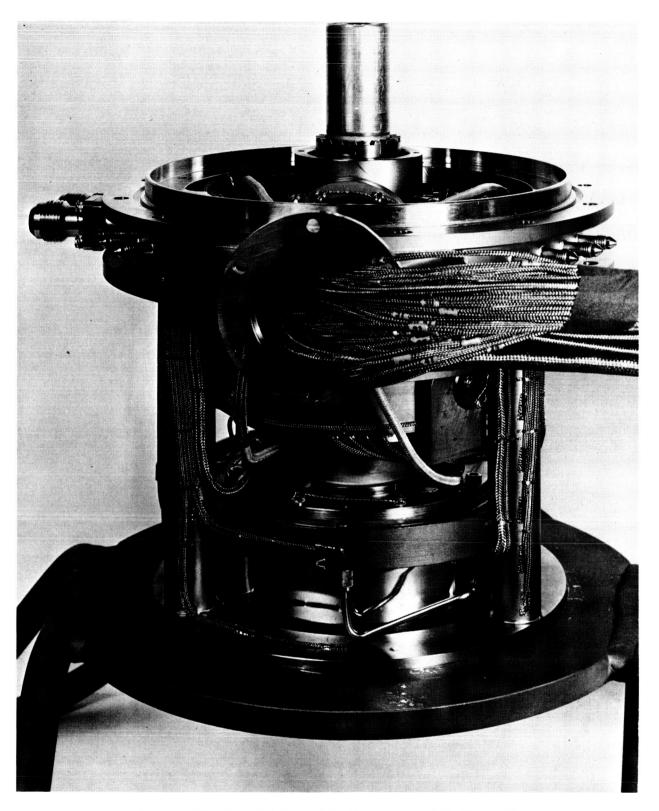
MAGNETIC SPEED PICKUP
FIGURE 42



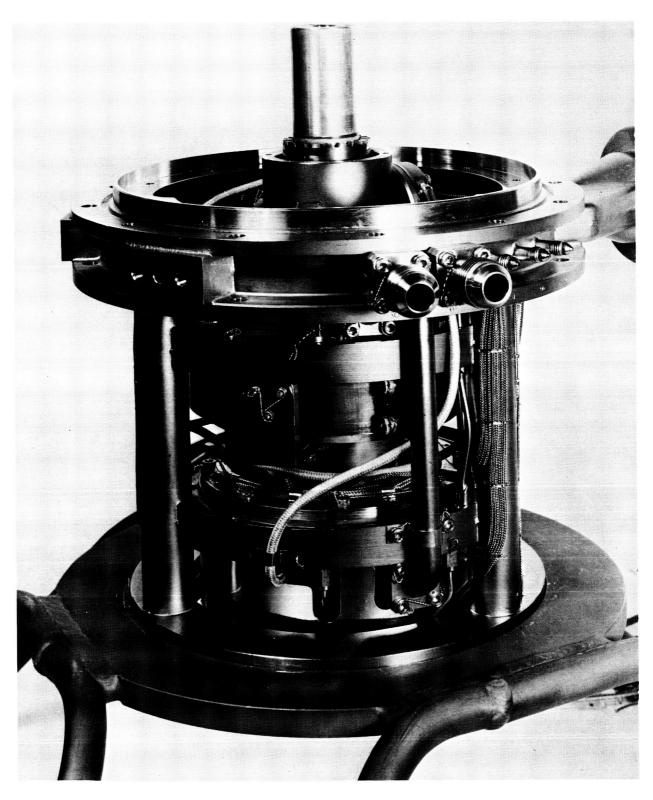
INSTRUMENTATION INSTALLATION, PARTIAL ASSEMBLY NASA GAS GENERATOR
FIGURE 43



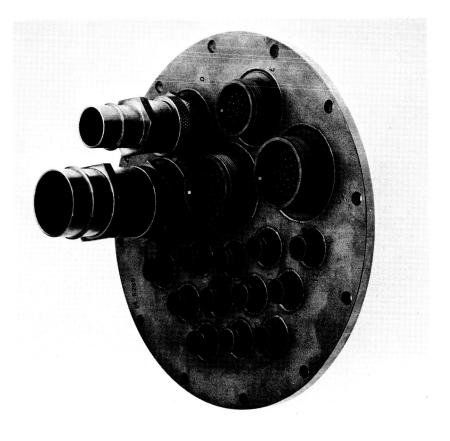
INSTRUMENTATION INSTALLATION, FINAL WIRING NASA GAS GENERATOR

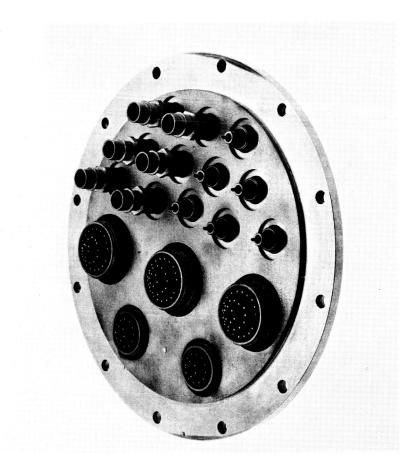


INSTRUMENTATION INSTALLATION, FINAL WIRING NASA GAS GENERATOR
FIGURE 45



INSTRUMENTATION INSTALLATION, FINAL WIRING NASA GAS GENERATOR
FIGURE 46





INSTRUMENTATION RECEPTACLE PLATE

In addition, the gas generator has been designed to accept gas bearing shoes with the following incorporated instrumentation:

- (a) Capacitance probes located in the bearing housing and situated such that they can monitor the bearing shoe leading edge of the first trailing shoe behind the resiliently mounted shoe on each bearing to determine pitch and roll characteristics of the bearings (four probes).
- (b) Capacitance probes built into the same shoes described above to determine the bearing shoe-to-shaft film thickness. The probe position will be on the pivot pitch axis as close to the pivot as possible (two probes).

This instrumentation would be utilized to determine gas bearing performance.

#### 4.0 FINAL GAS GENERATOR CONFIGURATION

### 4.1 Gas Generator Description

Figure 48 presents a simplified cross section of the final gas generator. For purposes of clarity, the unit may be considered to consist of eight groups of parts. These are (1) the rotating assembly, (2) the compressor-journal bearing assembly, (3) the turbine-journal bearing assembly, (4) the gimbal and thrust bearing assembly, (5) the compressor scroll and diffuser assembly, (6) the turbine scroll and nozzle assembly, (7) the main frame assembly, and (8) the mount assembly. In the following paragraphs, each of the above subassemblies is described. A list of the individual parts is presented in Table 5.

### 4.1.1 Rotating Assembly

The rotating assembly consists of the shaft, the compressor wheel, and the turbine wheel. The compressor wheel and the turbine wheel are positioned on the shaft with curvic couplings. A tension bolt, drawn up by the self-locking shaft nut and washer, provides the axial force required to hold the assembly together as a rigid body. The compressor wheel spinner completes the rotating assembly and is attached to the end of the tension bolt with a self-locking screw.

# 4.1.2 Compressor/Turbine Journal Bearing Assembly

The compressor/turbine journal bearing assembly consists of the compressor/turbine journal bearing carrier, two shoe-and-fixedmount assemblies, and one shoe-and-flexible-mount assembly.

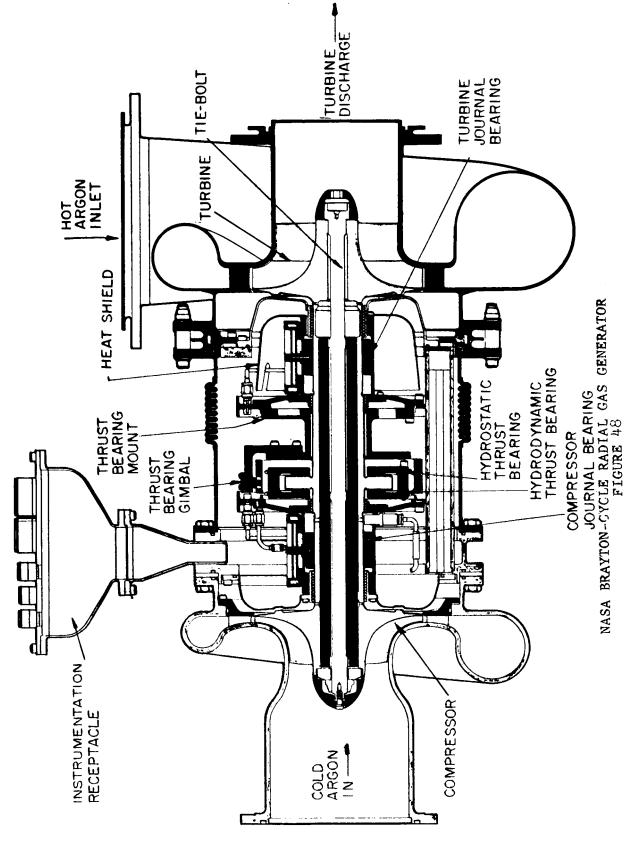


TABLE 5
NASA GAS GENERATOR PARTS LIST

DRAWING NO.	TITLE	USED ON	NO. REQD.
699301-1	GAS GENERATOR ASSEMBLY		
699302-1	Scroll Assembly, Turbine	699301-1	ļ
699303 - 1	Wheel, Turbine Impeller, Compressor	699301-1 699301-1	i
699304-1 <b>699307-1</b>	Seal, Static	699301-1	ī
699307-2	Seal, Static	**	ļ
699307-3 699308-1	Seal, Static Scroll Assembly, Compressor	699301-1	i
699309-1	Diffuser Assembly Compressor	699301-1	į
699310-1	Shaft Assembly, Gas Generator	699301 <b>-1</b> 699301 <b>-1</b>	1
699311-1 699312-1	Bolt, Tension Frame Assembly, Main	699301-1	ī
699313-1	Carrier Assembly, Turbine Bearing	699312-1	į
699314-1 600315-1	Carrier Assembly, Compressor Bearing Mount Assembly, Bearing	699312-1 699363- <b>1</b>	1 1 1 1 1 1 1 1
699315-1 699317-1	Mount Assembly, Bearing	699364- <b>1</b>	ī
699318-1	Tube Assembly, Thrust Bearing	699301-1	2
699320-1	Stator, Hydrostatic Thrust Bearing	699301 <b>-1</b> 699301 <b>-1</b>	1
699321-1 699324-1	Stator, Hydrodynamic Thrust Bearing Seal Assembly, Turbine	699301-1	î
699325-1	Seal Assembly, Compressor	699301-1	ļ
699326-1 600307 1	Shield, Turbine Radiation	699301-1 699301-1	i
699327-1 699328-1	Housing Assembly, Outer Housing Assembly, Instrumentation	699301-1	ī
699329-1	Plate Assembly, Connector Shoe Assembly, Bearing	699301-1	1
699330-1 699330-1	Shoe Assembly, Bearing Shoe Assembly Rearing	699363-1 699364-1	i
699333-1	Shoe Assembly, Bearing Tube Assembly, Metal Pressure Tap	699301-1	ž
699334-1	Spinner, Impeller Washer, Thrust	699301-1 699301-1	1
699335-1 699337-1	Probe. Capacitance (Shaft)	699301-1	4
699338-1	Probe, Capacitance (Shaft) Probe, Capacitance (Thrust Bearing)	699301-1	2
699339-1 600340-1	Pickup Assembly, Magnetic	699301-1 699313-1	3
699340-1 69934 <b>0-1</b>	Bellows, Duct Bellows, Duct	699314-1	1111111121142311111
699342-1	Rellows. Outer Housing	699327-1 **	Ţ
699343-1 699344-1	Flange, Turbine Inlet Flange, Turbine Outlet	**	i
699345-1	Spacer, Sleeve	699301-1	12 16
699345-1	Spacer, Sleeve	** 699301-1	10
699346-1 699348-1	Shim, Bearing Mount Shim, Bearing Mount	699301-1	4
699349-1	Shim, Turbine Scroll	699301-1	1
699354-1 699354-3	Shim, Capacitance Probe Shim, Capacitance Probe	699301-1 699301-1	2
699355-1	Shim, Magnetic Pickup	699301-1	3
699356-1	Base, Mounting	699301-1 600301-1	ļ
699357-1 699358-1	Bracket Assembly, Support Adapter, Fitting	699301-1 699301-1	3
699359-1	Bracket Assembly, Mounting	699301-1	2
699360-1 600363-1	Mount, Flexible Metal	699301-1 699301-1	2414231132242
699363-1 699364-1	Bearing, Matched Set Bearing, Matched Set	699301-1	ż
699365-1	Nut, Self Locking	699301-1	1
699366-1 699368-1	Tube Assembly, Diaphragm Mount Cover, Capacitance Probe Boss	699301-1 699301-1	1 4
699376-1	Tube Assembly	699301-1	
699410-1	Probe Assembly, Electrical Ground	699301-1 699 <b>410-</b> 1	1
699411-1 699412-1	Housing, Probe Support Stem Assembly, Probe	699410-1	î
699413-1	Guide, Stem	699410-1	1
699424-1 699434-1	Seal, Shaft Pivot, Thrust Bearing Mount	699301-1 699452-1	4
699435-1	Insert Pivot	699440-1	1 1 1 1 2 4 2 4 1 1 2 1 1
699436-1	Shim, Pivot	699452-1	4
699440-1 699441-1	Ring Assembly, Thrust Bearing Mount Spacer Assembly, Thrust Bearing	699452-1 699452-1	i
699443-1	Bushing, Pivot	699441-1	2
699451-1	Mount Assembly, Thrust Bearing	699452-1 699301 <i>-</i> 1	1,
699452-1	Gimbal, Matched Set	033201-1	•

## NASA GAS GENERATOR PARTS LIST (CONTD.)

DRAWING NO.	TITLE	USED ON	NO. REQD.
369745 369778 369779 369813	Shim, Sealing Spacer Flange, Compressor Outlet Flange, Compressor Inlet Seal, 'O"-Ring	699301 ** ** 699301	1 1 1 3
362-506-9013 362-506-9014 362-506-9015 362-522-9006 362-542-9002 473-010-9001 525-578-9003 655-601-9208	Gasket Gasket Gasket Gasket Gasket Lubricant Nut Screw	699301 699301 699301 699301 699301 699301 699301	1 1 2 16 AR 12 1
\$8171AP5 \$8171AP16 \$8171AP30 \$8171AP30 \$8171AP37	"0"-Ring "0"-Ring "0"-Ring "0"-Ring "0"-Ring "0"-Ring	699301 ** ** 699301 699301	1 1 1 1
\$8152BG46-0-240 \$8152BC46-0-240	Pin Pin	699312-1 699451-1	<b>1</b> 4
	COMMERCIAL PARTS		
AN4CH4A AN5CH4A AN5CH5A AN929-10S AN960C416L AN960C516 AN906C516L	Bolt Bolt Bolt Cap Assembly Washer Washer Washer	699301 699301 699301 699301 699301 699301	12 12 16 14 12
MS9068-015 MS20995C32 MS21045C4 MS21281-25 MS21288-06 MS21288-07 MS24585C51 MS24673-1 MS24673-2 MS24673-3 MS24673-9 MS24673-9 MS24673-11 MS24673-12 MS24674-1 MS24674-2 MS24674-2 MS24674-2 MS24674-7 MS24674-7 MS24677-1 MS24677-2 MS24677-2 MS24677-2 MS24678-15 MS24678-15 MS24678-15	"O"-Ring Lockwire Nut Screw	699301 699301 699301 699301 699301 699301 699312-1 699301 699410-1 699301 699401 699301 699301 699301 699301 699301 699301 699301 699301 699301 699301 699301 699301 699301 699301 699301	2 AR 12214 688 2448 2868 4 228 1228 1 128 1 128 1

A shim provides radial adjustment capability in each fixed-mount assembly. The axial center line of the rotating assembly is positioned by adjusting the two fixed mounts relative to the bearing carrier. A shim provides for bearing preload adjustment through the flexibly mounted shoe. Hydrostatic bearing gas is supplied to each fixed-mount bearing shoe by supply lines incorporated into the fixed mount and to the flexibly mounted bearing shoe by a tube assembly.

Two orthogonal capacitance probes, for monitoring shaft position, are provided at each bearing and adjusted by shims.

Three speed pickups are provided on the compressor journal bearing carrier and adjusted by shims.

### 4.1.3 Gimbal and Thrust Bearing Assembly

A gimbal assembly is provided to give the two thrust bearing stators alignment capability. Hydrostatic bearing gas is supplied individually to each thrust stator through tube assemblies.

A film-thickness capacitance probe and shim on each stator allow the bearing film thicknesses to be monitored during operation.

Attachment of the thrust bearing and gimbal assembly to the main frame is accomplished with the thrust bearing mount assembly into which are incorporated strain gauges for determining the thrust loads.

### 4.1.4 Compressor Scroll and Diffuser Assembly

The diffuser is attached by screws to the compressor scroll and sealed by an elastomer O-ring. The compressor discharge cooling-flow bleed fitting is located on the scroll discharge from which the cooling flow is ducted to the cooling inlet lines on the unit.

Axial face clearance between the wheel and the scroll is determined by sizing a shim located at the scroll mounting flange. The axial clearance was set at 0.012 inch during the design of the gas generator. From an aerodynamic consideration, a zero clearance would be optimum; however, a clearance of 0.002 inch per inch of wheel diameter can be utilized without serious performance penalty. From a mechanical consideration, it is advantageous to maintain large clearances so that, with rotor radial and axial displacements due to tolerance stackup, thermal growth, and flexible bearing displacements, the rotor does not rub the shroud.

For the acceptance test gas generator, the axial shroud clearance(for the turbine and the compressor) was increased over the design requirements to allow for test experience to be gained on the unit prior to extracting final efficiency figures.

# 4.1.5 Turbine Scroll and Nozzle Assembly

The turbine scroll and nozzle assembly is an integral onepiece assembly fabricated from an investment casting and several sheet-metal stampings. The axial face clearance between the turbine wheel and the scroll assembly is determined by sizing a shim located adjacent to the scroll mounting flange. The axial clearance was set at 0.014 inch during the design. However, this clearance was increased for the acceptance test, as discussed above.

### 4.1.6 Main Frame Assembly

The main frame assembly serves two functions. First and foremost, it provides a framework to which all major components or subassemblies are attached. This assures extreme accuracy in aligning those parts that have critical running clearances, such as the turbine scroll, the compressor scroll, the turbine labyrinth seal, and the compressor labyrinth seal.

Secondly, it contains all of the hydrostatic bearing gas supply lines, the cooling flow ducts and static pressure tap plumbing and provisions for routing and leading out all the electrical instrumentation lines.

## 4.1.7 Mount Assembly

An assembly is provided for mounting the unit in a vertical position with the turbine end down. The mount assembly consists of a base, a bracket, two flexible mounts, and two flexible mount brackets. The flexibility in the brackets and the two flexible mounts is intended to accommodate thermal expansions that occur during elevated-temperature operation of the unit.

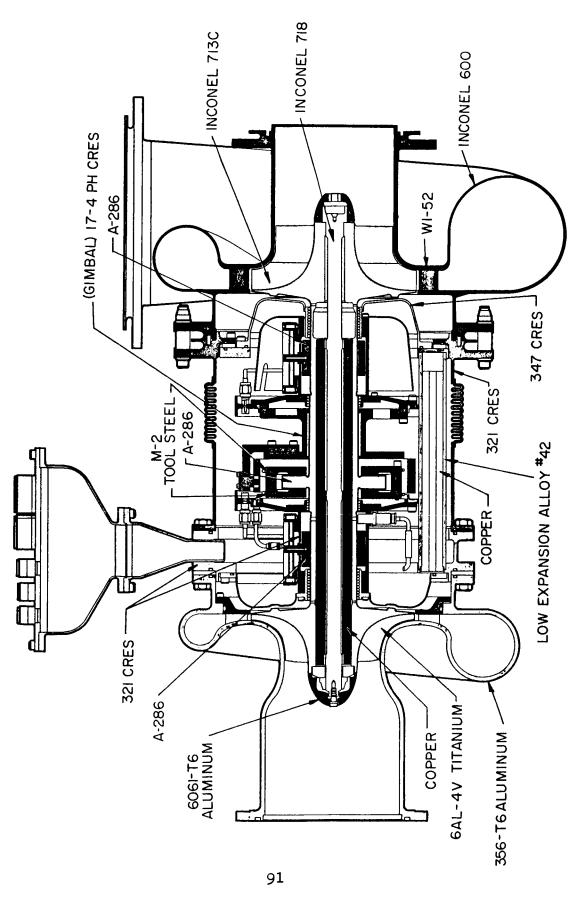
### 4.2 Component Configurations and Fabrication

The compressor and turbine aerodynamic components utilized in the final gas generator are described in detail in NASA Reports CR-54368 and CR-54367, respectively. The journal gas bearing configuration is described in Section 3.4.4 of this report, and the thrust bearing configuration is described in Section 3.5.1. Figure 49 shows a simplified cross-section of the gas generator with the materials of more pertinent parts noted.

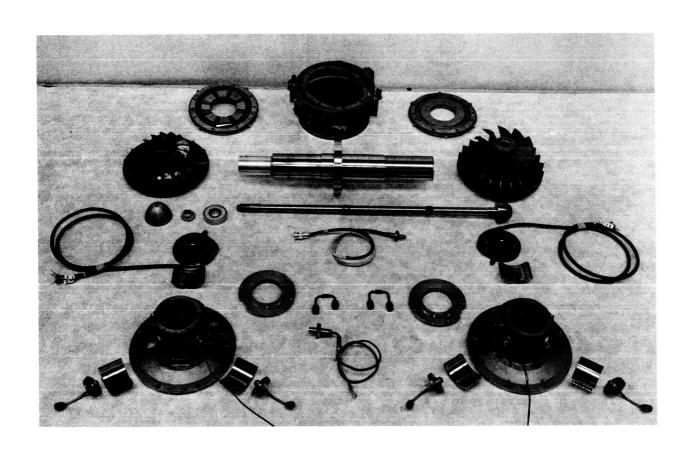
Fabrication of the gas generator components was initiated as the design of the components was finalized. Figures 50 and 51 show the major components after fabrication prior to the acceptance test. Details of some of the major components are shown in Figures 52 through 64, and Figure 65 shows the assembled gas generator.

### 4.3 Inspection

Inspection of the components of the delivery gas generators and final assembly were in accordance with the quality-assurance program established at the start of the program. Figures 66 and 67 show the Critical Parts Inspection and Serialization record for the turbine and compressor wheels of both delivery units. Figure 68 shows both sides of the Assembly Inspection and Laboratory Traveler for the gas generator, Serial No. P-A, assembled and operated for an acceptance test. The second gas generator, Serial No. P-B, was shipped as "component parts" at the request of the NASA; therefore, an Assembly Inspection and Laboratory Traveler is not available for this unit.



NASA BRAYTON-CYCLE RADIAL GAS GENERATOR WITH MATERIALS OF PERTINENT PARTS NOTED FIGURE 49



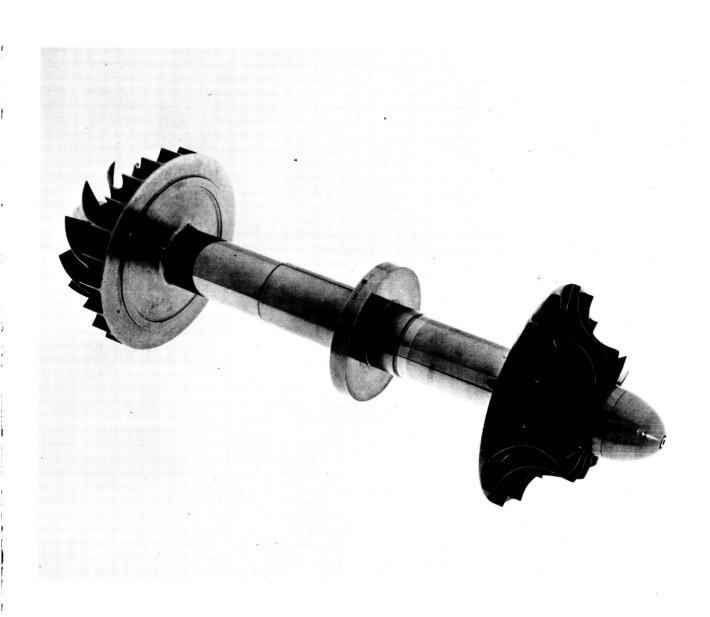
NASA GAS GENERATOR PART 699300 COMPONENT DISASSEMBLY



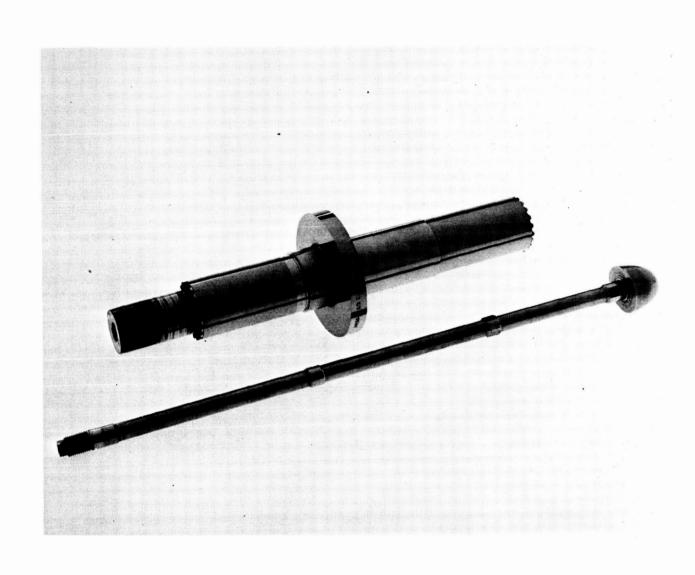
NASA GAS GENERATOR PART 699300 COMPONENT DISASSEMBLY



BEARING CARRIER AND FRAME ASSEMBLY
FIGURE 52



ROTATING COMPONENT GROUP ASSEMBLY FIGURE 53



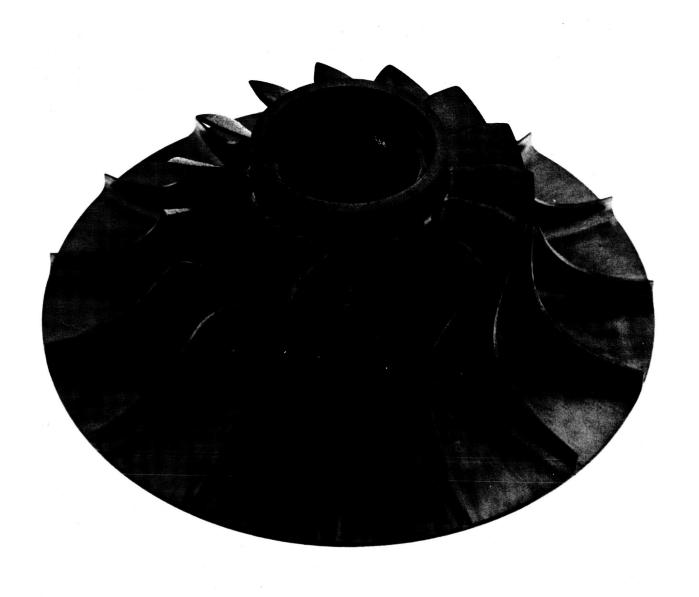
SHAFT ASSEMBLY AND TENSION BOLT FIGURE 54



TURBINE SCROLL AND NOZZLE ASSEMBLY
FIGURE 55



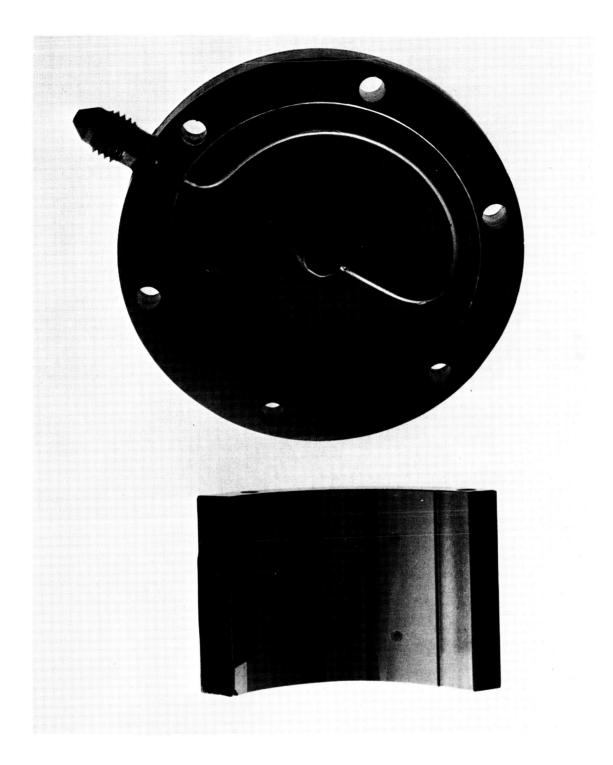
COMPRESSOR DIFFUSER ASSEMBLY FIGURE 56



COMPRESSOR IMPELLER FIGURE 57

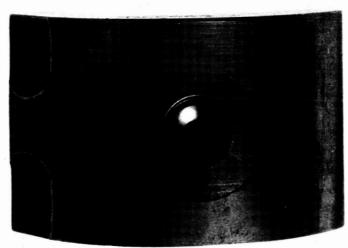


COMPRESSOR SCROLL ASSEMBLY FIGURE 58

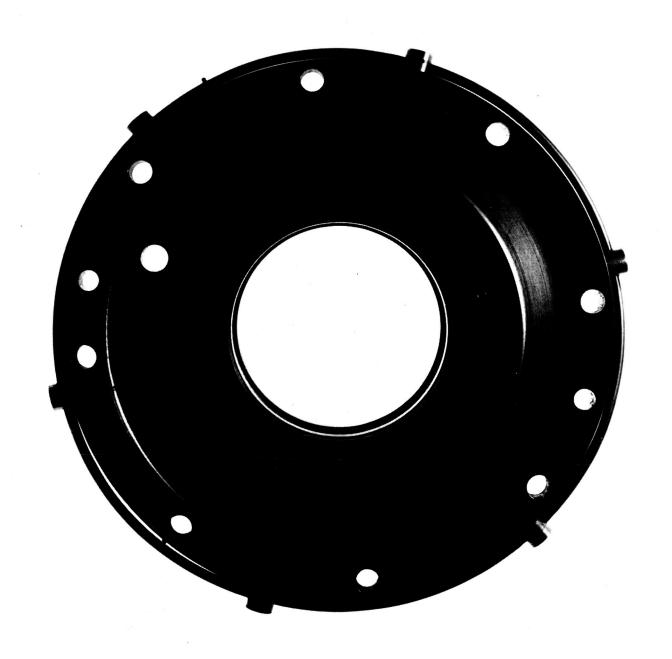


SHOE AND DIAPHRAGM ASSEMBLY, MATCHED SET FIGURE 59

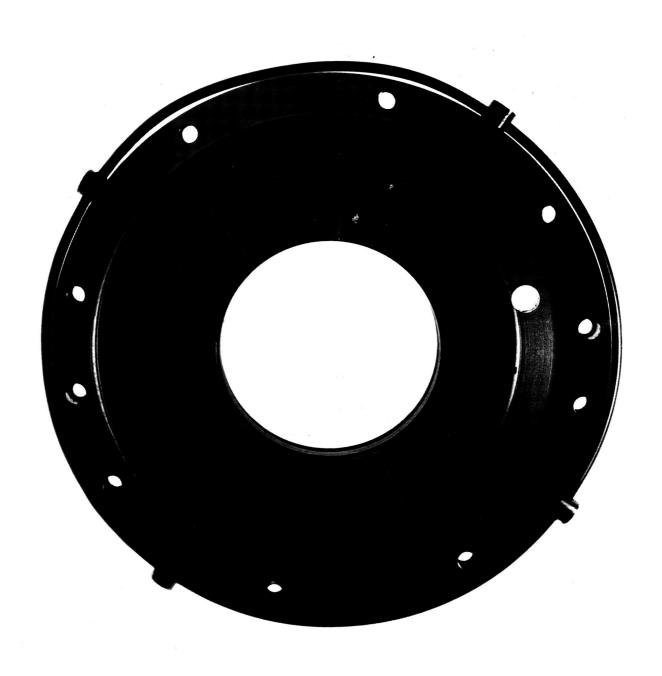




SHOE AND SOLID MOUNT, MATCHED SET FIGURE 60



HYDROSTATIC THRUST BEARING STATOR
FIGURE 61



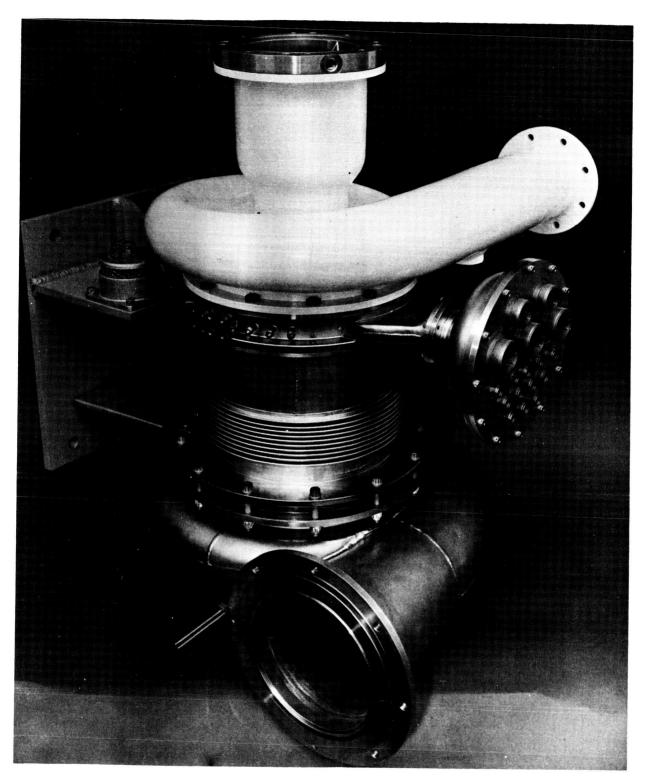
HYDRODYNAMIC THRUST BEARING STATOR
FIGURE 62



TURBINE AND COMPRESSOR BEARING CARRIERS FIGURE 63



OUTER HOUSING ASSEMBLY
FIGURE 64



NASA BRAYTON-CYCLE GAS GENERATOR FIGURE 65

## TURBINE WHEEL FOR GAS GENERATOR P-A

FORM P2741		RESEA	ксн		CRI	TICAL F	PART IN	SPECTIO	N AND SERIAL	IZATIO	RECOF	RD				
Forging/Cast	ing	No.	Ţ	С	/L	Serial	Number		O.S. GROWTH	DATA		Machine	d Part N	0.		C/L
* 3691	7 =	26-3		1	В	4.	X12-2	3				. 60	7936	3-1		N/c
Oper.		Date	Ins	p.		er,	Date	insp.	Control	After	After	Z/M		MRB Dis	p. Af ter	
Raw Mati.		Date	Sta	mp	Mach	. Part	Date	Stamp	Dim/Dia	G.R.	0.5.	After		Final	Assy	R&O
Dim,	2.	-22-64	<b>(</b>	<u> </u>	Dim.				6.0195		6.02	0	USE			
UIIII,					Di				6.04.			<del>-</del>	RWK			l
Ultra					Ultra/	Mch					<u></u>		SCP			
HT/Stress					   HT/St	7291	•						RTV			
111/311033	_	- (			111/5			ļ				10.0			UMBER	
Zyglo/Mag	2.	-22-611	C	<u> </u>	Zyglo	/Mag		<u> </u>				(A)		69 "	12.0	
Radiogr.	2	-22-64	("	>	Pull T	est						<b>*</b> • •	2338	2	ļ	
Heat No.	R	v055			Balan	ce	(	BAL	BAL							
2nd H.T.				i	Overs	peed	MAY 14	S	4/						<u> </u>	
Remarks:					Green	Run							"Raw M: Mfg. Co		<u> </u>	
					2nd O								* Mach.f	Part		
L					R.R.	No. IPT	# 131	<b>₊</b> 789	Part No. (	Changes			Mig. N			

# COMPRESSOR WHEEL FOR GAS GENERATOR P-A

Forging/Casting	Na		C/L I	Serial Nur	nhar		O.S. GROWTH	DATA		Machine	d Part No	*		C/L
* 379932-		'	J	4L-55			0.3. drowin	מאוא		l		 04 - 1	,	"A "
Oper.		insp.	Оре	<i>i</i> . ,		Insp.	Control	After	After	Z/M		MRB Dis	p. Af ter	
Raw Matt.	Date	Stamp	Mach.	Part L	Date	Stamp	Dim/Dia	G.R.	0.5.	After		Final	Assy ,	R&0
Dim. 1	0-14-6	u (2)	Dim.				5.476				USE			
O 1111.		1	JUIII.			<del> </del>	5.7/6/-	ļ	29/6	<b>Z</b>	RWK			<u> </u>
Ultila	3-14-6		Ultra/M	ch		İ					SCP			<u></u>
ANN 1 HT/Stress	0-14-6	(ر)	HT/Stre	ess							RTV	ITR N	UMBER	<u> </u>
Zyglo/Mag			Zyglo/I	Mag						(VIA	340	608		
Radiogr.			Pull Te	st			ļ			<u> </u>	ļ		<del> </del>	
Heat No. D-71	03		Balance			(Vg)				<u> </u>				
2nd H.T.			Overspe	ed 195	4.4	3	<u> </u>				<b>-</b>		}	
Remarks: Dup: Original o			Green R	Run				ļ 			*Raw M Mfg. C		4	
2-318 3.148 S.D.	236	r	2nd 0.5					<u> </u>	L	<u> </u>	• Mach.l	art		
5.848 J.D.	200 5/	1/10	R.R. No	D. 82	221		Part No. (	Changes			Mfg. N	0.		

FIGURE 66

## TURBINE WHEEL FOR GAS GENERATOR P-B

FORM P2741.	_			CRITI	CAL P	ART IN	PECTIO	N AND SERIAL	IZATIO	N RECO	RD		<del></del>		····
Forging/Casti	ng	No.		C/L S	Serial 1	Number		O.S. GROWTH	DATA		Machine	ed Part N	0.		C/L
. 3697	2	6-3	E	3	43	5-281	5				. 6	993	03-	./	N/C
Oper.		Date	Insp.	Oper		Date	Insp.	Control	After	After	Z/M		MRB DIS	p. Af ter	
Raw Mati.			Stamp	Mach.	Part	Date	Stamp	Dim/Dia	G.R.	0.5.	After	<u> </u>	Final	Assy	R&O
Dim.	2	-22-64	Ճ	Dim.	Ī			6.6700		2010.	Ł	USE			 
. ————								<b>6</b> , (y)		-		RWK		<u> </u>	ļ
Ultra	4			Ultra/Mc	:h					<b> </b>		SCP			ļ
HT/Stress				HT/Stre	33							RTV	<u> </u>	<u> </u>	<u> </u>
Zuele Ale -	2	-22-64	<b>a</b>	7 -1- 0				***************************************						UMBER	
Zygio/Mag	-			Zyglo/M	ag					C	ļ	233	82	<u> </u>	
Radiogr.	2	-22-64	◊	Pull Tes	st		BAI			<u> </u>		<u> </u>		ļ	
Heat No. 1	٤W	055		Balance		(	4	(34)						<u> </u>	
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Remarks:				Green Ri	un							*Raw Ma		l	
				2nd 0.S.								* Mach, F			<del></del>
				R.R. No.	IPT	# 13!	1789	Part No. C	hanges		· · · · · · · ·	Mfg. No			

COMPRESSOR WHEEL FOR GAS GENERATOR P-B

			CRI	TICAL	PART IN	SPECTIO	N AND SERIAL	IZATIO	RECOF	RD				
Forging/Casting	No.		C/L	Serial	Number		O.S. GROWTH	DATA		Machine	d Part N	0.		C/L
37.993	2-3	-	J	4	<b>L</b> 5	546				. (	99	304	-1	Ħ
Oper.	2.1.	Insp.	Op	er,		insp.	Control	After	After	Z/M		MRB Dis	p. Af ter	
Raw Matt.	Date	Stamp	Mach	. Part	Date	Stamp	Dim/Dia	G.R.	0.5.	After		Final	Assy	R&0
-Otm,	Y0-6*	(E)	Dim.			;	1990		3911		USE .			
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Zyglo/Mag			Zygfo	/Mag					<u> </u>	8	54061	· ED.	<u> </u>	
Radiogr.			Pull T	est				<u> </u>	<u></u>				<u> </u>	
Heat No.	<b>-7403</b>		Baland	ce		BAL								
2nd H.T.			Overs	peed	JUN 4	A							ļ	
Remarks:			Green	Run							*Raw Ma		L	
			2nd O	.S.					<u> </u>		* Mach, F			
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FIGURE 67

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ASSEMBLY INSPECTION AND LABORATORY TRAVELER, GAS GENERATOR FIGURE 68

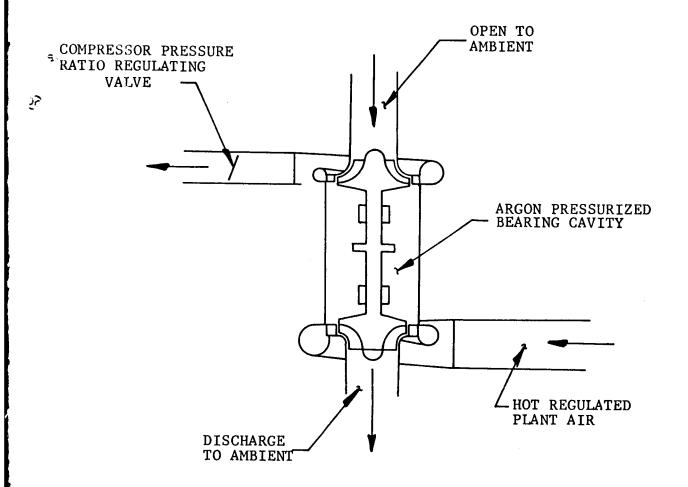
As can be seen from Figure 68, the first gas generator was run for a total of 5.58 hours during the acceptance test. This test is discussed in Section 5.0.

#### 5.0 ACCEPTANCE TEST

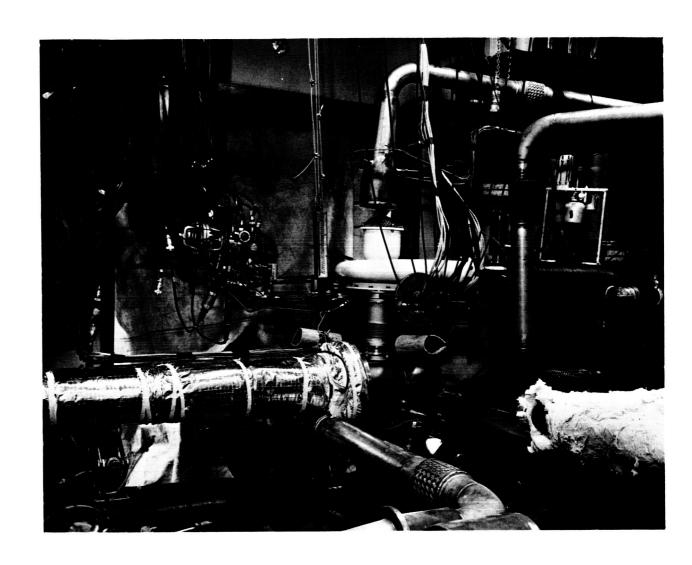
## 5.1 Test Installation

Operation of the gas generator for the acceptance test consisted of running the unit with plant air supplied to the turbing and with the compressor open to a clean air supply. Bearing and cavity pressurization was accomplished with filtered argon. Figure (schematically shows the acceptance test gas generator installation.

With the completion of the thrust bearing/gimbal assembly integration tests utilizing the gas generator frame test rig (see Section 3.5.2.2), the test frame rig was rebuilt with a set of wheels and scrolls to (a) determine the aerodynamic effects of the wheels upon the bearing system when subjected to coldacceptance-test conditions and (b) check out the cold-acceptancetest installation prior to acceptance testing the delivery gas generator. The initial test-cell installation is shown in Figures 70 and 71. Other than an initial rotating-group balance problem in the unit, the main problem was one of cell piping modifications in order to eliminate extraneous random vibrations fed into the unit by pneumatic ducting forces. A total of 15 hours of test time was logged in the turbine test cell without incident. At the conclusion of these tests, it was considered that the facility was suitable for the cold acceptance test of the NASA delivery gas generator No. 1. significant importance was the fact that the behavior of the bearing system, as established in the frame test-rig configuration with dummy rotating masses, was not in any way disturbed by the aerodynamic effect of the added wheels and scrolls.

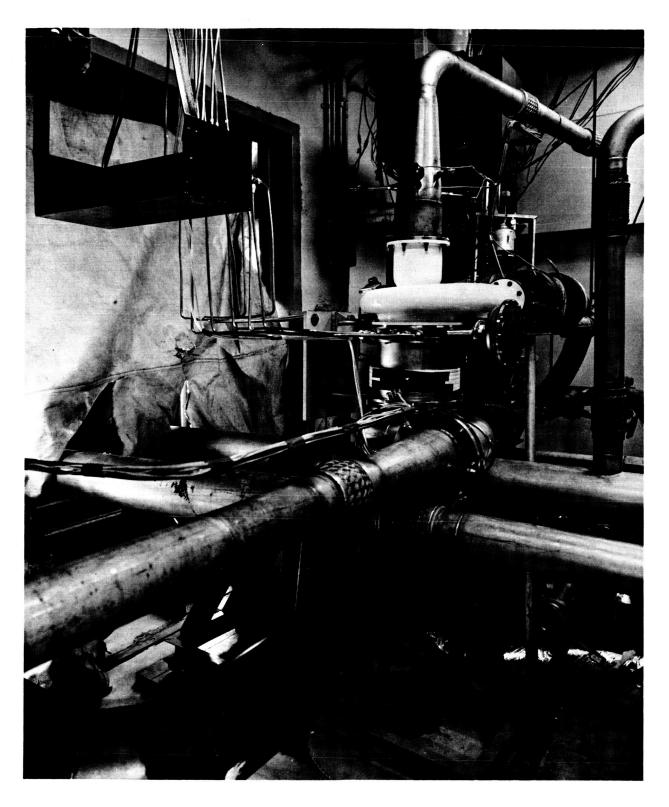


GAS GENERATOR ACCEPTANCE TEST INSTALLATION SCHEMATIC FIGURE 69



ACCEPTANCE TEST MOCK-UP OF GAS GENERATOR INSTALLED IN TEST CELL

FIGURE 70



ACCEPTANCE TEST MOCK-UP OF GAS GENERATOR INSTALLED IN TEST CELL FIGURE 71.

Testing of the gas generator in the turbine test cell indicated that the net aerodynamic thrust of the two wheels was in the reverse-thrust direction and that at 20,000 rpm the addition of temperature to the turbine inlet air in the range of 450 to 500°F allowed speed to be increased to 100 percent without subjecting the unit to excessive reverse-thrust loads. At 100 percent design speed, the resultant thrust load was of the order of 20 pounds in the reverse direction, which indicated that a balance of aerodynamic forces had been achieved. Test-plan requirements for the acceptance test were thus established.

## 5.2 Assembly of Gas Generator, First Shipping Unit

The first shipping unit, Serial No. P-A, Outline 699300, was assembled, and the assembly data on this unit was collected and documented in AiResearch Report APS-5174-R and forwarded to the NASA when the unit was shipped. The data relevant to the assembly is as follows:

Shaft-to-shoe geometric clearances.

Bearing mount shimming log, including bearing preload settings, axial center shift, and seal concentricities.

Turbine and compressor axial shroud clearance data.

Capacitance probe and speed pickup shimming log.

Capacitance probe calibrations (6)

Gas generator thrust-mount load calibration.

Compressor and turbine journal bearing flexible-mount diaphragm calibrations (2).

Instrumentation pin call-out data.

Instrumentation location schematic

For safety considerations, the axial shroud clearances were increased over the design requirements to allow for test experience to be gained on the unit prior to extracting final efficiency figures. The data presented will allow the NASA to remove material from the shims in successive stages in achieving the end objective during closed-loop testing.

# 5.3 Initial Test and Calibration of First Shipping Unit

The shipping unit, after basic buildup, was equipped with the dummy masses and tie-bolt from the frame test rig. rotating group was then subjected to gas bearing evaluation tests in order to determine unit performance and to check out the instrumentation, particularly the proximity probes and certain specific thermocouples. Checkout included operation of the bearing journals and thrust faces hydrostatically, with the reverse thrust bearing being calibrated for film thickness versus load. The normal thrust bearing was also calibrated in the same manner when in the hydrostatic regime. A single-point calibration was also established when the normal thrust bearing was run hydrodynamically. calibrations have been reported in AiResearch Report APS-5174-R. The journal bearings were also operated in the hydrostatic regime. Additional thrust-transfer checks were performed in both directions with hydrostatic operation, between normal and reverse-thrust faces at 35,000, 30,000, 25,000, and 20,000 rpm. Overspeed was also checked in the hydrostatic mode to 42,000 rpm. All of the tests conducted in the bearing test cell were performed without any problems occurring. The unit proved to have even better performance than had been demonstrated previously on the companysponsored test rig, particularly with respect to shaft balance and thrust stator face operating clearances.

## 5.4 Acceptance Test of First Shipping Unit

The test-plan procedure had been adequately established by the prior test series undertaken with the modified frame test rig. The installation configuration in the test cell was similar to Figures 70 and 71. Figures 72 and 73 show the test instrumentation setup of the Wayne-Kerr proximity meters in relation to the test unit and the visual recording data outputs, respectively.

After installation, the unit was subjected to a test run to full speed, hydrostatically, to determine that the rotational balance of the shaft components was acceptable. The balance was proven to be satisfactory.

The final instrumentation hook-up for recording purposes was arranged as follows:

Tape Recorder: Seven channels, to record the four

orthogonal and two thrust probes, with speed and voice combined on one channel.

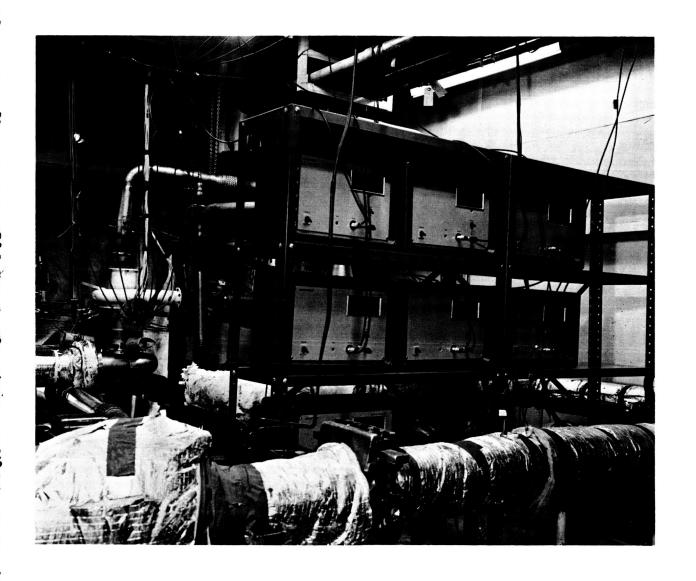
Oscillograph Recorder: 20 channels, to record 16 thermo-

couples, 3 strain gauges, and speed.

Visual Readout: The remaining thermocouples chosen for

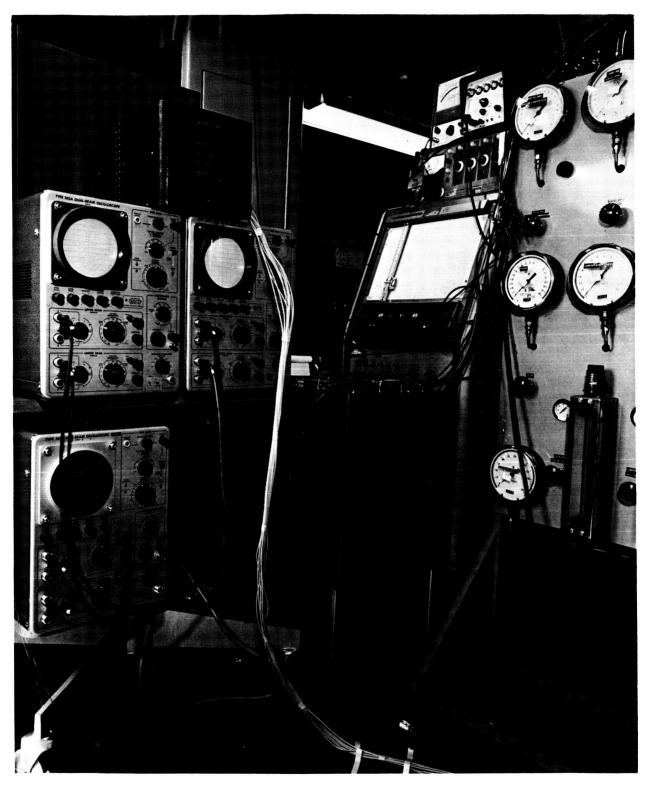
safety reasons. Shaft and thrust surface proximity probes, speed, temperature, and strain-gauge output on the thrust mount through an X-Y

plotter.



WAYNE-KERR PROXIMITY METERS NASA GAS GENERATOR ACCEPTANCE TEST

FIGURE 72



GAS BEARING CONTROL PANEL AND INSTRUMENTATION NASA GAS GENERATOR ACCEPTANCE TEST FIGURE 73

The acceptance test was run in accordance with the test plan and successfully demonstrated the requirements of the contract. This test was witnessed by the NASA representatives, and the unit was accepted.

Although performance demonstration was not required, measurements were required to establish steady-state operation and control during tests. Figure 74 shows the test-cell log sheet for the acceptance test on the Serial No. P-A gas generator, and Figures 75 and 76 show the data log sheets for the acceptance test. Figure 77 shows the tape and oscillograph log sheets.

	QUALIFICATION TEST LOG	
E.W.O. No.2	109-27/36-16-1006 Date 9-9-65 Test Cell or Station No. D-10	27
	699301 Model No. CCGG-20-1 Unit Serial No. P-	9
Development	Engineer 13 HEATH Technician BUNDEIL Grp. Ldr. TIM	MEIC
Test Type	DEU. Test Schedule APS 5173 -R Modification -	~
TIME START STOP	Event	J.0.
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	CALIBERTED BLL INSTRUMENTATI	DN
	RUN #1 TAPE # 800 (c-140	
	70N 1 1111 400 (5-170	4
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		(22)
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	PROFILE TO DOCOO 121714 & INCIZIBIA	SP-
1030	March TO 38500 RP17	<del> </del> -
1035	DATA: COLL. 13B	
10.42	FRINOUED FOURN PRO. H.S. ARGO & INCR. TURB. INFET TO 475°F	N -
	& INCR. TUICES. INLET TO 4750F	CSC
1045	DATA COEL CC	<del></del>
11:15	DATA COLL DO	
11.45	DATA COKK FE	
1215	DATA COLL GG	<del> </del>
1.375	DATA COLL H.H	
13:45	DATA COLL T.I	
14:13	DATA COLL TJ.	
1445	DATA COLL, KK	
15.15	DATA COLL LL	<del></del>
15-45	PATURNED ANDROSTATIC BROON TO	
	Tauren Bres (GO PSKG)	<del></del>
1550	REDUCED SAR TO 20000 IZPH & TO	als
	DATA (TAPE) CYERY TWO MIN. FOR	TEN .
	MIN	-
1554	INCR COOLING FIGON FLOW TO GO SCF	<b>2</b>
1/0/	SHUT DOWN	<del>                                     </del>
7600	SHUTDOWN	
	REMOURD UNIT FROM CELL	
SUMMARY:	Total Running Time 5 hrs. 35 min. Ref. Data Page	-
	Total Manual Starts Engineering Starts	milera

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NASA GAS GENERATOR ACCEPTANCE TEST LOG SHEET

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NASA GAS GENERATOR ACCEPTANCE TEST LOG SHEET

FIGURE 76 1. 124

### UNIT ASSEMBLY 699300, SERVAL FP-A PX1959 AIRESTARCE MANUFACTURING COMPANY OF ARIZONA PATE 9-9-63 LOCATION D-107 JOS TYPE Acceptance Test TECH. RAE ENG. WS SUBJECT: NABA GAS GENERATUR TAPE LOG SEERT TAPE NO. 800 FREQUENCY 27KC PR-600 RECORDER TYPE EWO 3409-27136-16-1002 RWO 6701 TAPE SPEED 15 IPS TRACE 1 DE PH SPEED - COMMENTARY 2 DR WAYNE-KERR PROBE #21 DR PH CONTRESSOR END DR PH 3 (ZiO " " # #22 . 85 1 DR TURBINE END " #23 DR DR SM DR SM DR NOEMAL THRUST SURFACE " #24 4 (E) " #25 \* #26 1 PR REVERSE THRUST SURFACE L TIME CALIBRATE CHANNELS 2-7 FOR ONE VOLT 1020 RUN UP TO 20,000 RPH TO STABILIZE UNIT 1030 RUN UP TO 36,500 RPH 1042 RUN UP TO 36,500 RPH 1041 RUN HYDROTHANIC ON JOURNALS 1115 STRADY STATE RUNNING HYDRODYNAMIC @ 38,500 RPM DP #1 1030 RUR UP TO 38,300 RPM TO STABILIZE UNIT DP #2 1042 RUR MYDRODYNAMIC ON JOURNALS DP #3 1115 STRADY STATE RUNNING HYDRODYNAMIC @ 38,500 RPM DP #4 1145 DP #5 1215 DP #6 1245 DP #7 1315 DP #8 1345 DP #9 1415 DP #10 1445 DP #11 1515 DP #11 1515 DP #12 1547 ADD HYDROSTATIC AIR AND DECREASE SPEED TO 20,000 RPM DP #14 1555 DP #15 1547 DP #14 1555 DP #15 1547 DP #15 1547 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559 DP #15 1559

# Afficements Manufacturing Company of Actions.

# OSCILLOGRAPH RECORDING LOS

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00391		1030		DP 10. 1	RIM UP TO 38,500 RPM		2
00392		1012		DP NO. 2	RUN HYDRODYNAMIC OM JOHRNALS		62
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00394		1145		DP NO. 4	HYDRODYNAMIC AT 38,500 RPM		-
00395		1215	L	DP NO. 5	HYDRODYNAMIC AT 38,500 RPM		T
00396		1245		DP NO. 6	HYDRODYNAMIC AT 38,500 RPM		
00397		1315	L	DP NO. 7	HYDRODYNAMIC AT 38,500 RPM		
00398		1395		DP NO. 8	HYDRODYNAMIC AT 38,500 RPM		
00399	ļ.,	1815		DP. NO. 9	HYDRODYNAMIC AT 38,500 RPM		1
00400		1445		DP NO. 10	HYDRODYNAMIC AT 38,500 RPM		-2
10400		1515		DP NO. 11	HYDRODYNAMIC AT 38,500 RPM		6
00402		1535		DP NO. 12	HYDRODYNAMIC AT 38,500 RPM		
00403		1557		DP NO. 13	ADDED HYDROSTATIC ARGON AND		- 310
					REDUCE SPRED TO 20,000 RPM		600
DONON		1555		DP NO. 14	STEADY STATE AT PO.000 RPM		
00105		1557		DP NO. 15	STEADY STATE AT 20,000 RPH		
00406		1559		DP NO. 16	STEADY STATE AT 20,000 RPH		T
00107	L	1601		DP NO. 17	STEADY STATE AT 20,000 RPM		1
80400		1602			ROLL DOWN		(C24)
			$\exists$				
X1406		1	1	1			

FE1403

#### Hillesearch Manufacturing Company of Arizona

#### OSCILLOGRAPH RECORDING DATA

					Tochatetani Skund						
					Manuff & Broonses						
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UNI	REEA 1	MBLY 699300, SERIA	T NO	. P-A							

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1	SPEED	TACH	10,000 RPM/IN	0.0				L					${\mathbb T}$		2 er£			
				T											e eri			
2	THERMOCOUPLE NO. 1	7-1	200°F/IN 0°F AT	1,0											0.54			
	THERMOCOURIE NO. 2	1-2	200°F/IN OF AT	1.0			l	<u> </u>					ᆚ		975		L	
.6	THERMOCOUPLE NO. 4		200°F/IN 0°F AT	1.0		مـــــــ	ļ					Ц	_			Ļ		
.7	THERMOCOUPLE NO. 6	7-4	200°F/IN O°F AT	2.0				ļ	<u> </u>		_		_	4_	K_028_	ļ	L	
	THERMOCOUPIE NO. 7	1-5	200°F/IN 0°F AT	2,0	<u> </u>		ļ		$\sqcup$		lacksquare	Ц	_	٠	923			
9	THERMOCOUPLE NO. 10	7-6	200°F/IN O°F AT	2.0	<u> </u>		·				<b> </b>	Ш				<u> </u>		
11,	THURRHOCOUPLE NO. 11	T-7	200°F/IN O°F AT	3.0	L		- بـــر	<del> </del>		<u> </u>	<u> </u>	Ш	4	4				
10	THERMOCOUPLE NO. 13	T-8	200°F/IN O°F AT	_ 3.0	Ļ		<u> </u>	↓	_	ļ		Ш		4_	988	<u> </u>		
16	THERMOCOUPLE NO. 14	7-9	200°F/IN 0°F AT	3.0	<del> </del>		<b></b>	↓	<u> </u>			Щ	-	-		<del> </del>		
18	THERMOCOUPLE NO. 15	T-10	200°F/IN O°F AT	4.0	<u> </u>			<u> </u>		<u> </u>	<u> </u>		_1	4-	A	<del> </del>		
10	THERMOCOUPLE NO. 16	7-11	200°F/IN O°F AT	14.0	<u> </u>	<u> </u>	L	Ļ	L	L	L_		$\sqcup$		A-023-	↓		
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26	THERMOCOUPLE NO. 19		200°F/IN 0°F AT	5.0	_		<b></b>	₩-	ļ	<b> </b>	<b>-</b>	_	├}-		<u> </u>	┼		
27	THERMOCOUPLE NO. 20		200°F/IN 0°F AT	5.0	_	<b>├</b> ─-	<b></b>	<b>├</b>	<b>├</b>		<del> </del>	<u> </u>	╌	-	<u> </u>			
26	THERMOCOUPLE NO. 21	T-3A	200°F/IN O°F AT	5.0	<u> </u>	ļ	·	<u> </u>	├		₩	L.	$\vdash \vdash$		<u> </u>	┼		
29	THERMOCOUPLE NO. 92	T-4A	200°F/IN 0°F AT	6.0	ļ	┼⁴	·		ļ		╁	L.,	╀╃	_	• • • • •	╁	ļ	
	<del></del>		<u> </u>		1_	4		↓	├	<b> </b>	-	_	1	4-	* ***	+		
31	TUEBINE BRG. LOAD	ATT NO.	10 LBS/IN	6,0	<b>├</b>	<b>_</b>	345, "- 14 L	4	56K	_	CHEA		7-4-		4 984	—	<u> </u>	ZERO W/MORHAL PRELO
33	COMPR BRO TOAD	ATT NO.	10 LBS/IN	7.9	<b>!</b>	<b>_</b>	335m- 8AL	4	56X	1 5	HCREA	THO	14A	<u> </u>	k 978	↓		ZERO W/HORMAL PRELO
34	THRUST BRG. LOAD	ATT NO.	200 <sub>0</sub> "/III	8,0	<u> </u>		1954"	↓	1000	عــــا	<u> + 11</u>				924	<u> </u>	ļ	ZERO-ROTOR WI.
<del>- 1000</del>			<u> </u>		١	1_0	<u> </u>	↓	╙	<u> </u>	<b>↓</b>	DIN	BC I	DE	2 072	↓_	<u> </u>	<u> </u>
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			<u> </u>		1_	1_2	4	↓	<b>_</b>	١	1		Ш	4-	982	—		<u> </u>

NASA GAS GENERATOR ACCEPTANCE TEST TAPE AND OSCILLOGRAPH LOG SHEETS FIGURE 77

#### APPENDIX I

## Glossary

The following is a list of terms used throughout the report:

g = conversion factor = 32.2 ft 1b per 1b sec<sup>2</sup>.

m = molal gas flow rate, lbs mol per sec.

r = compressor pressure ratio

 $r_{t}$ , = gas-generator turbine pressure ratio

r<sub>t</sub>, = power-turbine pressure ratio

C = difference between bearing shoe radius and journal
 radius. inches

D = compressor-wheel diameter, inches

D<sub>f</sub> = gas-generator turbine-wheel diameter, inches

 $E_{R}$  = recuperator effectiveness

L = bearing axial length, inches

M = molecular weight, lbs per lb mol

 $N_1$  = gas-generator shaft speed, rpm

 $N_2$  = power-turbine shaft speed, rpm

 $N_{S_{2}}$  = compressor shaft speed

 $N_{S_{+}}$  = gas-generator turbine specific speed

 $N_{S_{to}}$  = power-turbine specific speed

P<sub>1</sub> = compressor inlet pressure, lbs per sq ft

 $P_3$  = gas-generator turbine inlet pressure, lbs per sq ft

R = bearing journal radius, inches

 $R_1$  = universal gas constant = 1545 ft-1bs per 1b-mol  ${}^{\circ}R$ 

 $T_1$  = compressor inlet temperature,  ${}^{\circ}R$ 

 $T_3$  = gas-generator turbine-inlet temperature,  ${}^{\circ}R$ 

W = mass flow rate, lbs per sec

 $\beta = \frac{\text{turbine pressure ratio}}{\text{compressor pressure ratio}} = \frac{r_{t_1} \times r_{t_2}}{r_c}$ 

 $\delta$  = inlet pressure, psia/14.7 psia

γ = ratio of gas specific heats = 1.667 for monatomic gases

 $\theta_1 = \gamma - 1/\gamma$ 

 $\theta$  = inlet temperature,  ${}^{\circ}R/518.7{}^{\circ}R$ 

 $\eta_c$  = compressor adiabatic efficiency

 $\eta_{cy} = \frac{power-turbine\ shaft\ power\ output}{gas-cycle\ input\ rate}$ 

 $\eta_{t_1}$  = gas-generator turbine adiabatic efficiency

 $\eta_{t_2}$  = power-turbine adiabatic efficiency